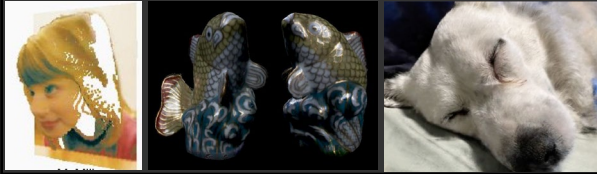


Image-Based Rendering

CSE 274, Lecture 4: IBR and Light Fields

Ravi Ramamoorthi

<http://www.cs.ucsd.edu/~ravir>



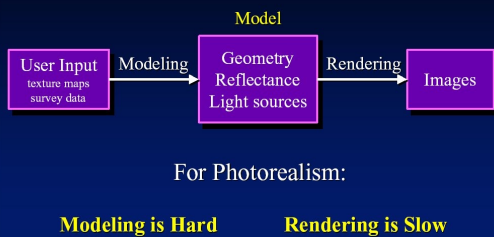
1

To Do

- Project Milestone Reports Due ??
- 1-2 page PDF or weblink with at least one image or video to show current results
- Describe project, progress to date, and final proposal based on results

2

Traditional Modeling and Rendering



Next few slides courtesy Paul Debevec; SIGGRAPH 99 course notes

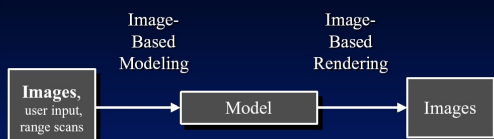
3



Can we model and render this?
What do we want to do with the model?

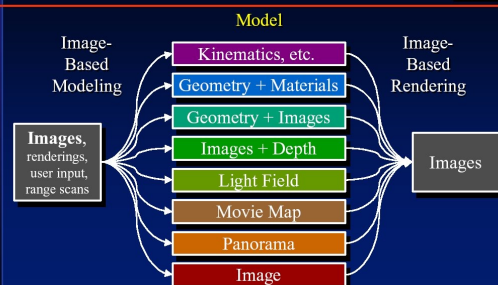
4

Image-Based Modeling and Rendering



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The Spectrum of IBMR



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IBR: Pros and Cons

- Advantages
 - Easy to capture images: photorealistic by definition
 - Simple, universal representation
 - Often bypass geometry estimation?
 - Independent of scene complexity?
- Disadvantages
 - WYSIWYG but also WYSIAYG
 - Explosion of data as flexibility increased
 - Often discards intrinsic structure of model?
- Today, IBR-type methods also often used in synthetic rendering (e.g. real-time rendering PRT)
 - General concept of data-driven graphics, appearance
 - Also, data-driven geometry, animation, simulation
 - Spawned light field cameras for image capture

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Image-Based Models: What do they allow?



Model	Movement	Geometry	Lighting
Geometry + Materials	Continuous	Global	Dynamic
Geometry + Images	Continuous	Global	Fixed
Images + Depth	Continuous	Local	Fixed
Light Field	Continuous	None	Fixed
Movie Map	Discrete	None	Fixed
Panorama	Rotation	None	Fixed
Image	None	None	Fixed

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IBR: A brief history

- Texture maps, bump maps, environment maps [70s]
- Poggio MIT 90s: Faces, image-based analysis/synthesis
- Mid-Late 90s
 - Chen and Williams 93, View Interpolation [Images+depth]
 - Chen 95 Quicktime VR [Images from many viewpoints]
 - McMillan and Bishop 95 Plenoptic Modeling [Images w disparity]
 - Gortler et al, Levoy and Hanrahan 96 Light Fields [4D]
 - Shade et al. 98 Layered Depth Images [2.5D]
 - Debevec et al. 00 Reflectance Field [4D]
 - Inverse rendering (Marschner, Sato, Yu, Boivin, ...)
- Today: IBR hasn't replaced conventional rendering, but has brought sampled and data-driven representations to graphics

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Game #1: increase the dimensionality

2D rgb	texture
2D rgbz	range image
2.5D rgb α z	layered depth images
4D rgb	light field / Lumigraph
4D rgbz	array of range images
4.5D rgb α z	layered light fields

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Game #2: replace the quantity represented

4D rgb	light field / Lumigraph
$\{u, v, s, t\}$	
5D rgb	plenoptic function
$\{x, y, z\} \times \{\theta, \phi\}$	
6D ρ	free-space BRDF field
$\{u, v, s, t\} \times \{\theta_s, \phi_s\}$	
7D ρ	BRDF volume
$\{x, y, z\} \times \{\theta_s, \phi_s, \theta_r, \phi_r\}$	

© 1997 Marc Levoy

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Outline

- Overview of IBR
- Basic approaches
 - Image Warping
 - [2D + depth. Requires correspondence/disparity]
 - Light Fields [4D]
 - Survey of some early work

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View Interpolation for Image Synthesis

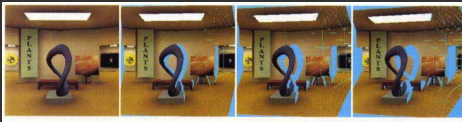


Fig. 3 A source image viewed from a camera rotated to the right.

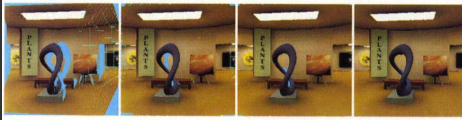


Fig. 5 (a) Holes from one source image, (b) holes from two source images, (c) holes from two closely spaced source images, (d) filling the holes with interpolation.

Chen and Williams. View Interpolation for Image Synthesis. SIGGRAPH 93

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Images as a Collection of Rays



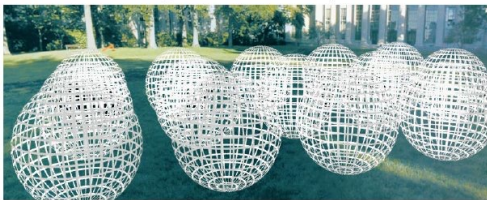
An image is a subset of the rays seen from a given point
- this "space" of rays occupies two dimensions

Warping slides courtesy Leonard McMillan, SIGGRAPH 99 course notes

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The Plenoptic Function

✓ The set of rays seen from all points ...

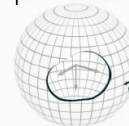


$$p = P(\theta, \phi, x, y, z, \lambda, t)$$

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Image-based rendering is about

...reconstructing a plenoptic function from a set of samples taken from it.



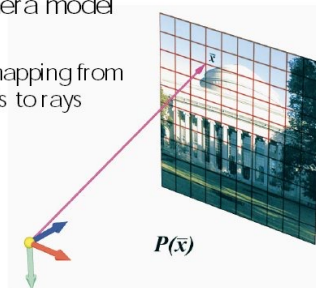
✓ Ignoring time, and selecting a discrete set of wavelengths gives a 5-D plenoptic function

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Where to Begin?

✓ Pinhole camera model

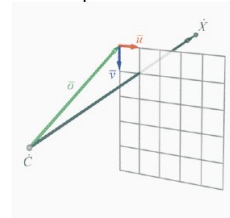
- Defines a mapping from image points to rays in space



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Mapping from Rays to Points

✓ Simple Derivation

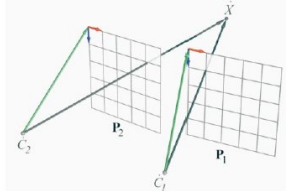


$$P = \begin{bmatrix} u_x & v_x & o_x \\ u_y & v_y & o_y \\ u_z & v_z & o_z \end{bmatrix}$$

$$\dot{X} = \dot{C} + t P \vec{x}$$

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Correspondence

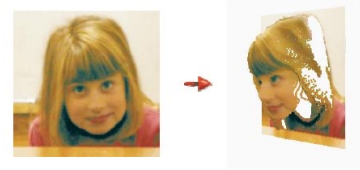


$$\begin{aligned}\dot{C}_2 + t_2 P_2 \vec{x}_2 &= \dot{C}_1 + t_1 P_1 \vec{x}_1 \\ t_2 P_2 \vec{x}_2 &= \dot{C}_1 - \dot{C}_2 + t_1 P_1 \vec{x}_1 \\ t_2 \vec{x}_2 &= P_2^{-1} (\dot{C}_1 - \dot{C}_2) + t_1 P_2^{-1} P_1 \vec{x}_1 \\ \frac{t_2}{t_1} \vec{x}_2 &= \frac{1}{t_1} P_2^{-1} (\dot{C}_1 - \dot{C}_2) + P_2^{-1} P_1 \vec{x}_1 \\ \vec{x}_2 &\doteq \underbrace{\frac{1}{t_1} P_2^{-1} (\dot{C}_1 - \dot{C}_2)}_{\vec{c}_{21}} + \underbrace{P_2^{-1} P_1}_{H_{21}} \vec{x}_1\end{aligned}$$

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Warping in Action

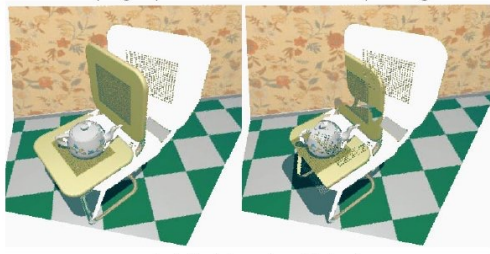
✓ A 3D Warp



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Visibility

✓ The warping equation determines where points go...

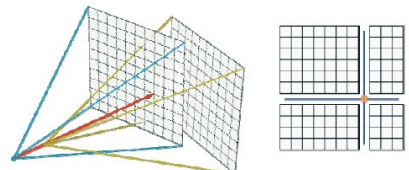


... but that is not sufficient

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Partition Reference Image

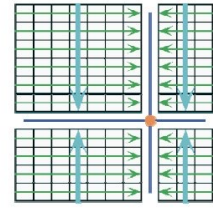
✓ Project the *desired* center-of-projection onto the reference image



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Enumeration

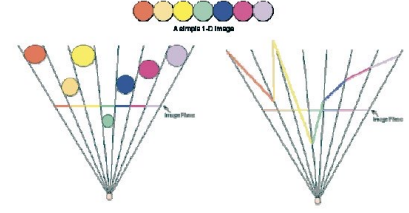
- ✓ Drawing toward the projected point guarantees an *occlusion compatible* ordering
- ✓ Ordering is consistent with a painter's algorithm
- ✓ Independent of the scene's contents
- ✓ Easily generalized to other viewing surfaces
- ✓ No auxiliary information required



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Reconstruction

- ✓ Typical images are discrete, not continuous
- ✓ An image can be formed by different geometries



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Outline

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 - *Light Fields [4D]*
 - Survey of some early work

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Light Field Rendering

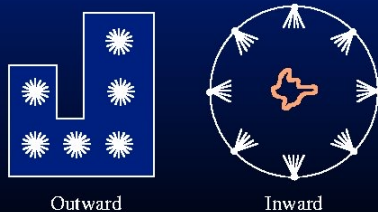
Marc Levoy Pat Hanrahan



Computer Science Department
Stanford University

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Apple's QuickTime VR



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Generating New Views



Problem: fixed vantage point/center


One Solution: view interpolation

- Interpolating between range images (Chen and Willams, 1993)
 - Correspondences and epipolar analysis (McMillan and Bishop, 1995)
- > Requires depths or correspondences:
must be extracted from acquired imagery
relatively expensive and error-prone morph

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Light Fields

Gershun's and Moon's idea of a light field:  
Radiance as a function of a ray or line: $L(x, y, z, \theta, \phi)$

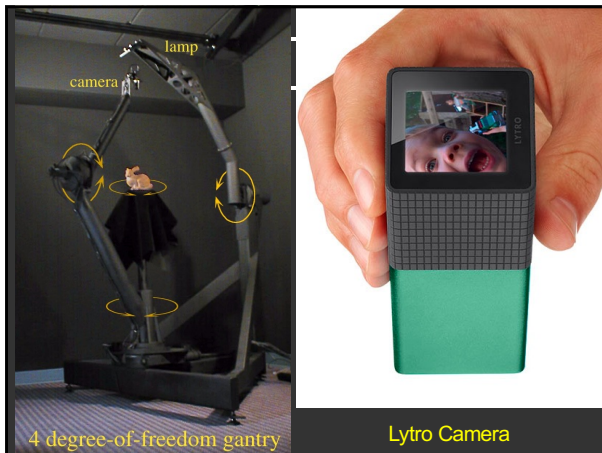
- In "free space" (no occluders) 5D reduces to 4D
 - Exterior of the convex hull of an object
 - Interior of an environment
- Images are 2D slices
 - Insert acquired imagery
 - Extract image from a given viewpoint 

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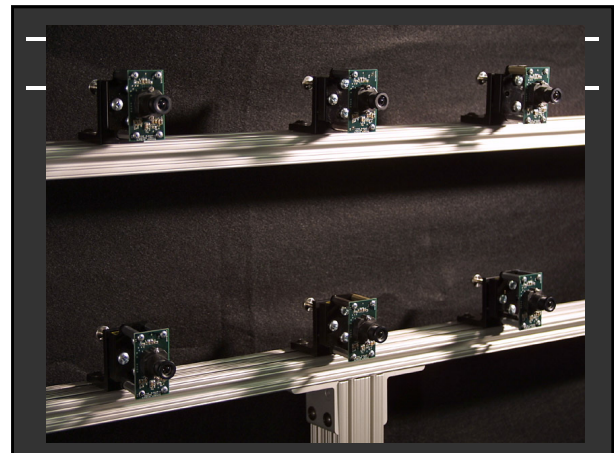
4D Light Field



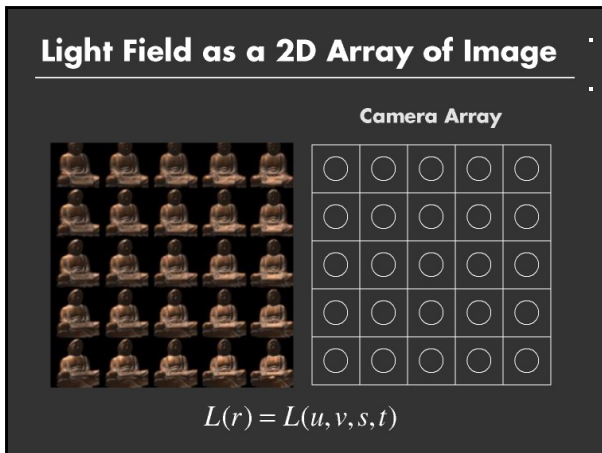
30



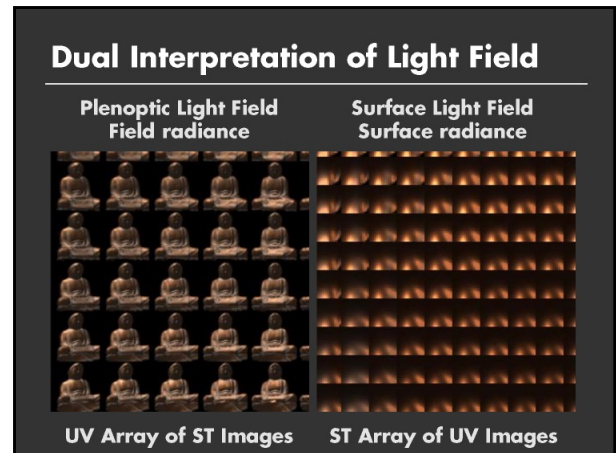
31



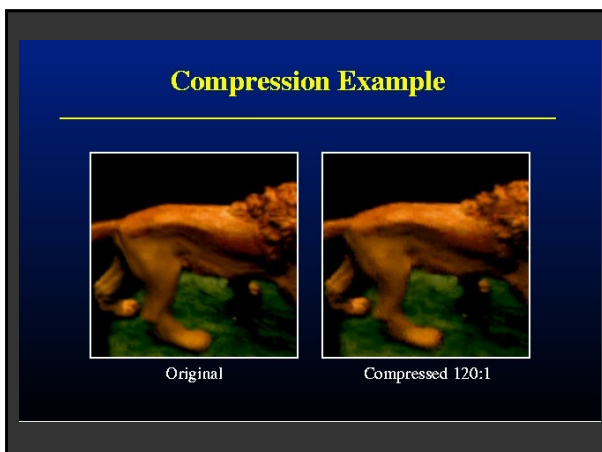
32



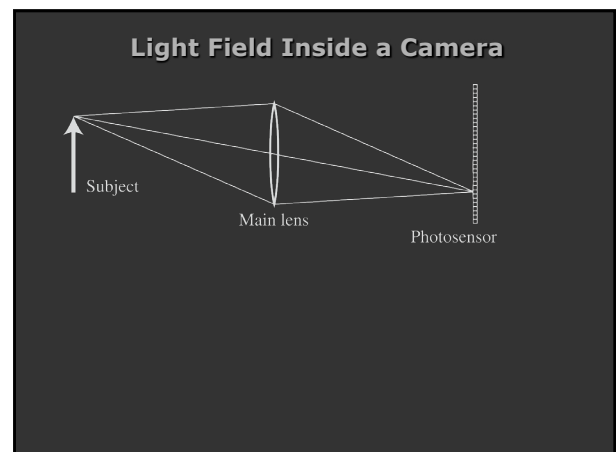
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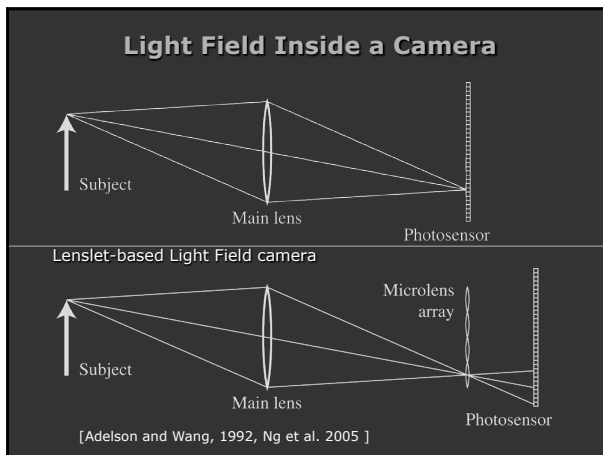
34



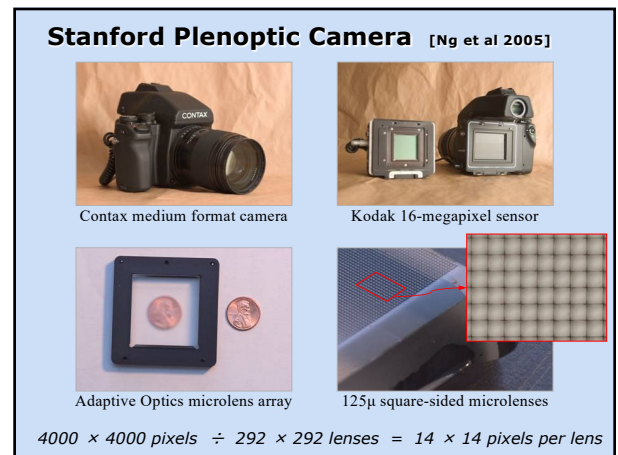
35



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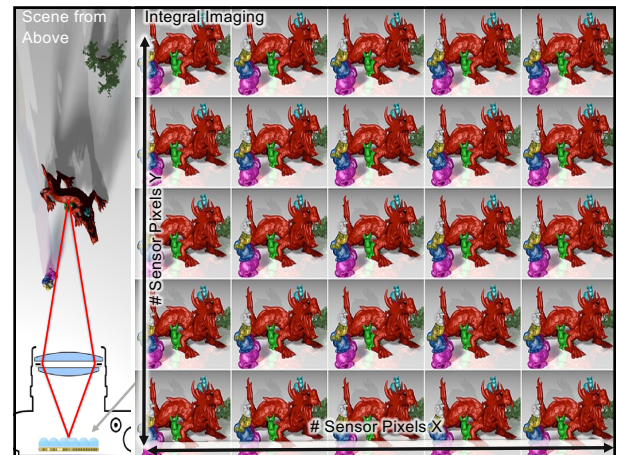
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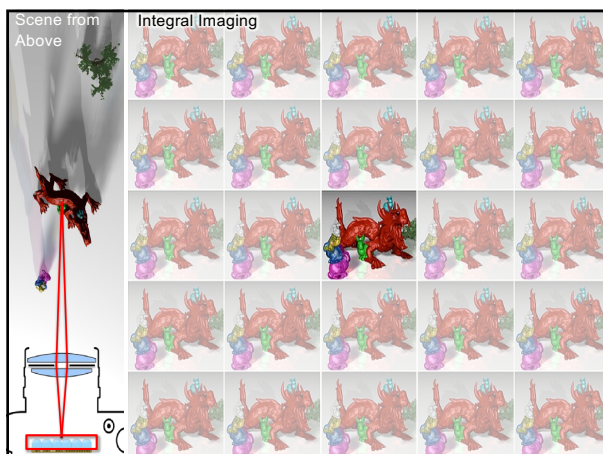
38



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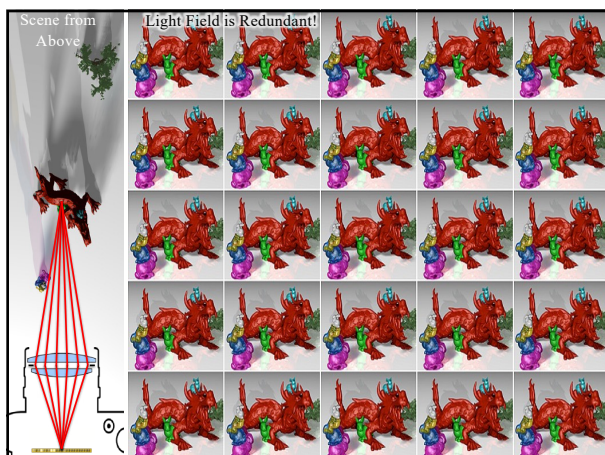
40



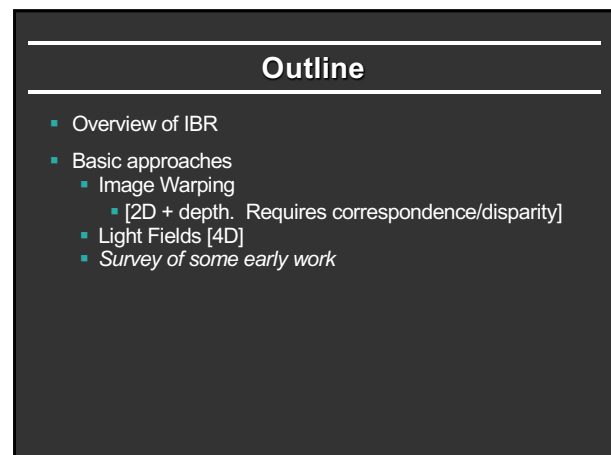
41



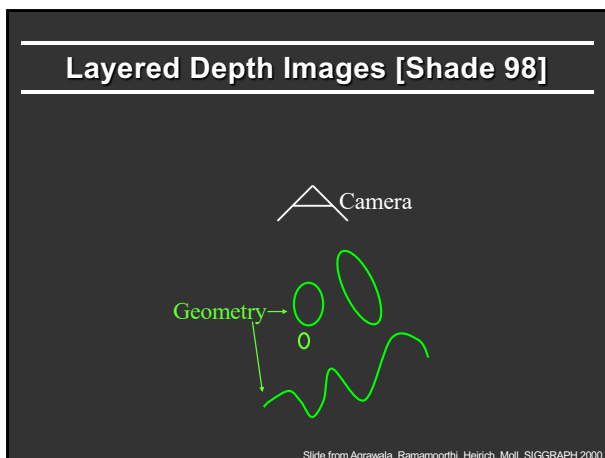
42



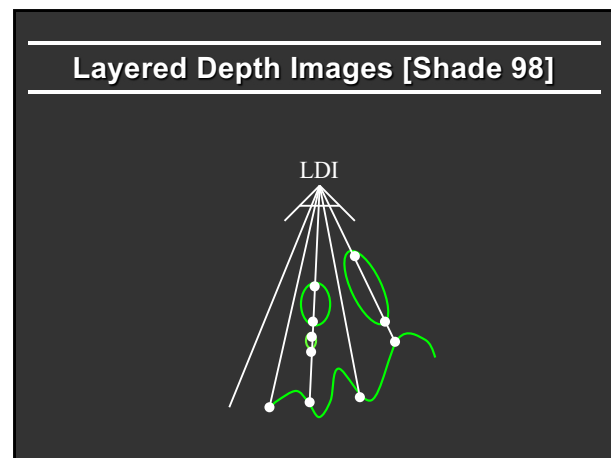
43



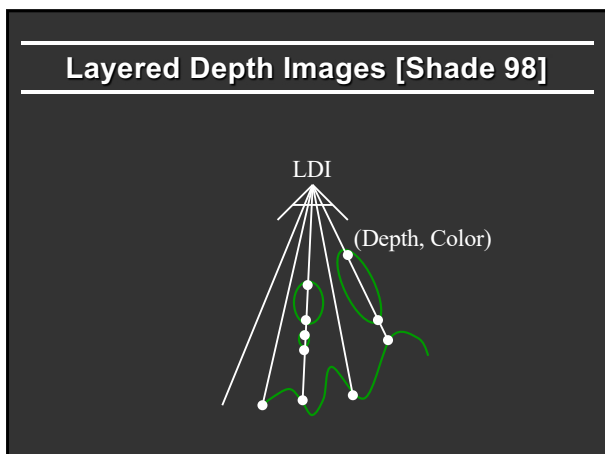
44



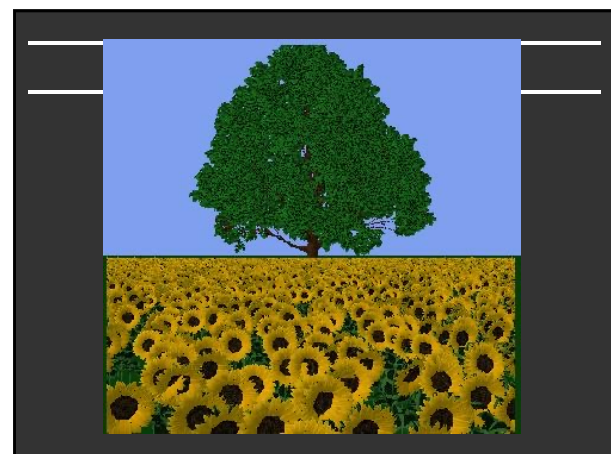
45



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Surface Light Fields

- Miller 98, Nishino 99, Wood 00
- Reflected light field (lumisphere) on surface
- Explicit geometry as against light fields. Easier compress



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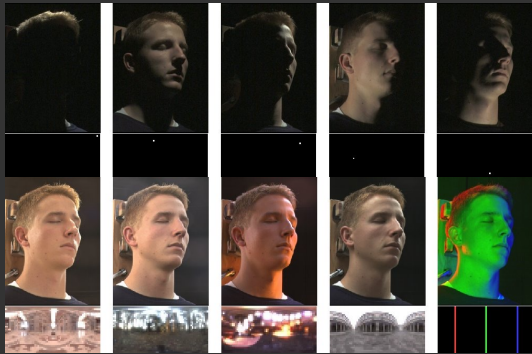
Acquiring Reflectance Field of Human Face [Debevec et al. SIGGRAPH 00]

Illuminate subject from many incident directions



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Example Images



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