

## Sampling and Reconstruction of Visual Appearance

CSE 274 [Winter 2018], Lecture 3

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### Motivation: Monte Carlo Rendering

- Key application area for sampling/reconstruction
- Modern methods for denoising now popular
- 1-3 order of magnitude speedups in mature area
- Denoising now standard in production rendering
- This week: Basic background in rendering
  - Reflection and Rendering Equations
  - Monte Carlo Integration
  - Path Tracing (Basic Monte Carlo rendering method)
  - A review for those who have taken CSE 168

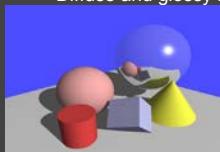
## Illumination Models

### Local Illumination

- Light directly from light sources to surface
- No shadows (cast shadows are a global effect)

### Global Illumination: multiple bounces (indirect light)

- Hard and soft shadows
- Reflections/refractions (already seen in ray tracing)
- Diffuse and glossy interreflections (radiosity, caustics)



Some images courtesy Henrik Wann Jensen

## Caustics

Caustics: Focusing through specular surface



- Major research effort in 80s, 90s till today

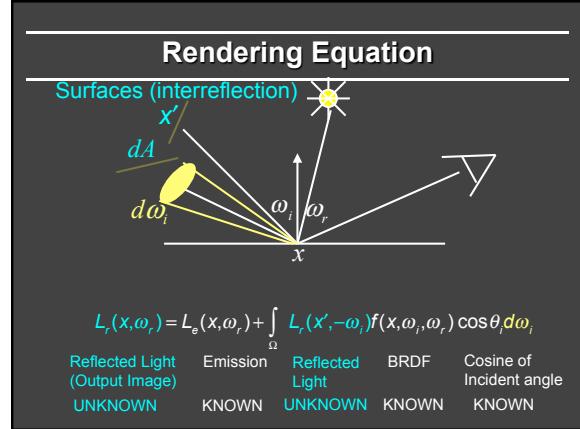
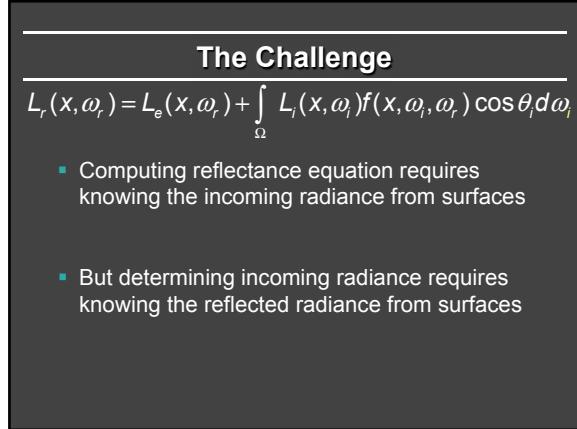
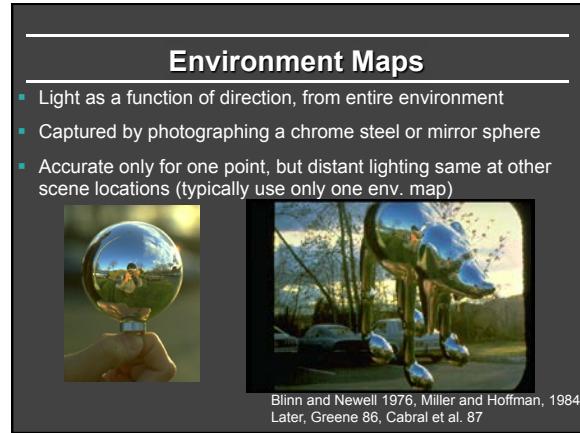
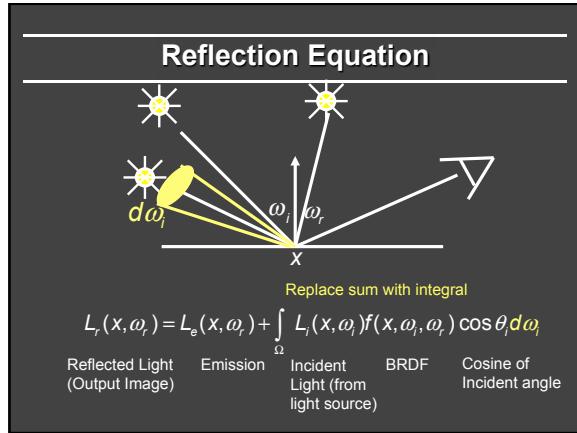
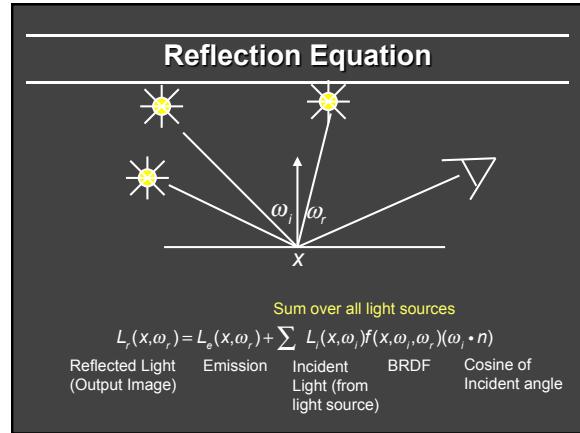
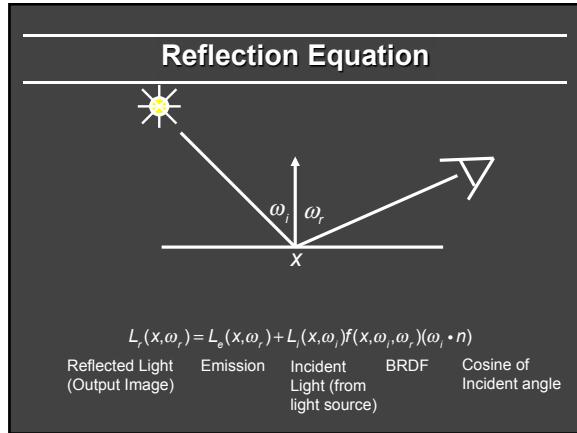
## Overview of lecture

- **Theory** for all global illumination methods (ray tracing, **path tracing**, radiosity)
- We derive **Rendering Equation** [Kajiya 86]
  - Major theoretical development in field
  - Unifying framework for all global illumination
  - Introduced Path Tracing: core rendering method
- Discuss existing approaches as special cases

Fairly theoretical lecture (but important). Not well covered in textbooks (though see Eric Veach's thesis). See reading if you are interested.

## Outline

- **Reflectance Equation**
- **Global Illumination**
- **Rendering Equation**
- As a general Integral Equation and Operator
- Approximations (Ray Tracing, Radiosity)
- Surface Parameterization (Standard Form)



## Outline

- Reflectance Equation (review)
- Global Illumination
- Rendering Equation
- *As a general Integral Equation and Operator*
- *Approximations (Ray Tracing, Radiosity)*
- Surface Parameterization (Standard Form)

## Rendering Equation (Kajiya 86)



Figure 8. A sample image. All objects are neutral grey. Color on the objects is due to caustics from the green glass balls and color bleeding from the base polygons.

## Rendering Equation as Integral Equation

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Reflected Light (Output Image)	Emission	Reflected Light	BRDF	Cosine of Incident angle
UNKNOWN	KNOWN	UNKNOWN	KNOWN	KNOWN

Is a Fredholm Integral Equation of second kind [extensively studied numerically] with canonical form

$$l(u) = e(u) + \int l(v) K(u, v) dv$$

Kernel of equation

## Linear Operator Theory

- Linear operators act on functions like matrices act on vectors or discrete representations

$$h(u) = (M \circ f)(u) \quad M \text{ is a linear operator.} \\ f \text{ and } h \text{ are functions of } u$$

- Basic linearity relations hold  $a$  and  $b$  are scalars  $f$  and  $g$  are functions

$$M \circ (af + bg) = a(M \circ f) + b(M \circ g)$$

- Examples include integration and differentiation

$$(K \circ f)(u) = \int k(u, v) f(v) dv$$

$$(D \circ f)(u) = \frac{\partial f}{\partial u}(u)$$

## Linear Operator Equation

$$l(u) = e(u) + \int l(v) K(u, v) dv$$

Kernel of equation  
Light Transport Operator

$$L = E + KL$$

Can be discretized to a simple matrix equation [or system of simultaneous linear equations] ( $L, E$  are vectors,  $K$  is the light transport matrix)

## Solving the Rendering Equation

- Too hard for analytic solution, numerical methods
- Approximations, that compute different terms, accuracies of the rendering equation
- Two basic approaches are ray tracing, radiosity. More formally, Monte Carlo and Finite Element. Today Monte Carlo path tracing is core rendering method
- Monte Carlo techniques sample light paths, form statistical estimate (example, path tracing)
- Finite Element methods discretize to matrix equation

## Solving the Rendering Equation

- General linear operator solution. Within raytracing:
- General class numerical **Monte Carlo** methods
- Approximate set of all paths of light in scene

$$L = E + KL$$

$$IL - KL = E$$

$$(I - K)L = E$$

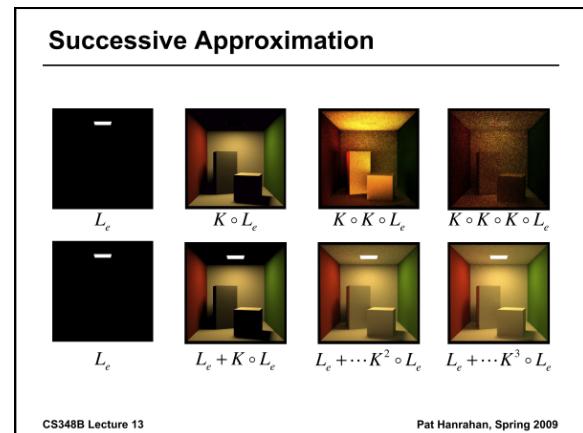
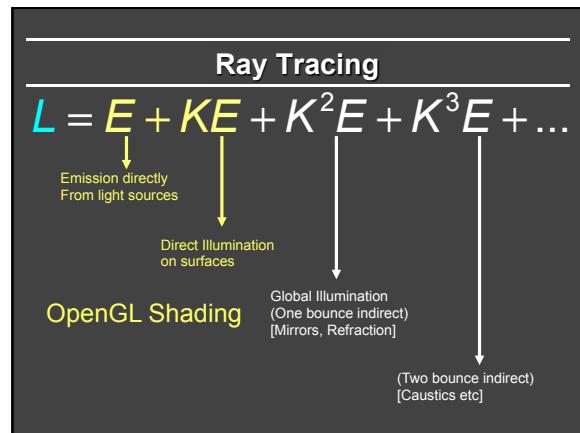
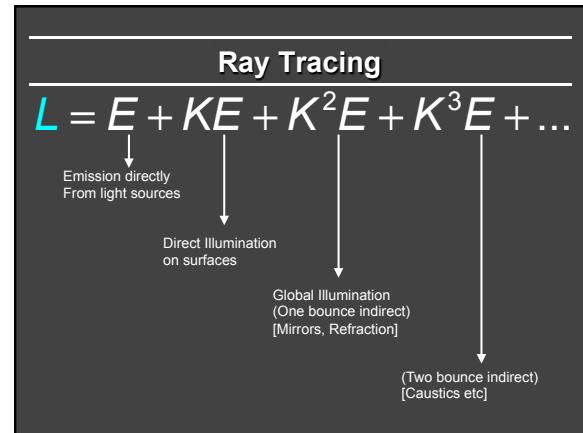
$$L = (I - K)^{-1}E$$

Binomial Theorem

$$L = (I + K + K^2 + K^3 + \dots)E$$

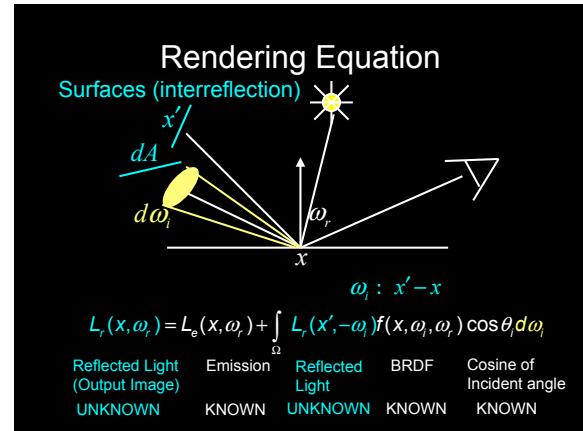
$$L = E + KE + K^2E + K^3E + \dots$$

Term n corresponds to n bounces of light



## Outline

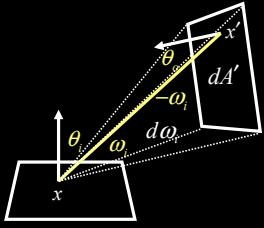
- Reflectance Equation (review)
- Global Illumination
- Rendering Equation
- As a general Integral Equation and Operator
- Approximations (Ray Tracing, Radiosity)
- Surface Parameterization (Standard Form)**



## Change of Variables

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Integral over angles sometimes insufficient. Write integral in terms of surface radiance only (change of variables)



$$d\omega_i = \frac{dA' \cos \theta_o}{|x - x'|^2}$$

## Change of Variables

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Integral over angles sometimes insufficient. Write integral in terms of surface radiance only (change of variables)

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\text{all } x' \text{ visible to } x} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \frac{\cos \theta_i \cos \theta_o}{|x - x'|^2} dA'$$

$$d\omega_i = \frac{dA' \cos \theta_o}{|x - x'|^2}$$

$$G(x, x') = G(x', x) = \frac{\cos \theta_i \cos \theta_o}{|x - x'|^2}$$

## Rendering Equation: Standard Form

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Integral over angles sometimes insufficient. Write integral in terms of surface radiance only (change of variables)

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\text{all } x' \text{ visible to } x} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \frac{\cos \theta_i \cos \theta_o}{|x - x'|^2} dA'$$

Domain integral awkward. Introduce binary visibility fn  $V$

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\text{all surfaces } x'} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) G(x, x') V(x, x') dA'$$

Same as equation 2.52 Cohen Wallace. It swaps primed and unprimed, omits angular args of BRDF, - sign.

Same as equation above 19.3 in Shirley, except he has

no emission, slightly diff. notation

$$G(x, x') = G(x', x) = \frac{\cos \theta_i \cos \theta_o}{|x - x'|^2}$$

## Summary

- **Theory** for all global illumination methods (ray tracing, path tracing, radiosity)
- We derive **Rendering Equation** [Kajiya 86]
  - Major theoretical development in field
  - Unifying framework for all global illumination
- Discuss existing approaches as special cases

## Motivation: Monte Carlo Integration

Rendering = integration

- Reflectance equation: Integrate over incident illumination
- Rendering equation: Integral equation

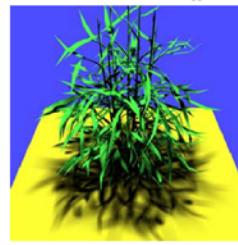
Many sophisticated shading effects involve integrals

- Antialiasing
- Soft shadows
- Indirect illumination
- Caustics

Most Sampling/Reconstruction treats actual rendering as a black box. But still helpful to know some basics

## Example: Soft Shadows

$$E(x) = \int_{H^2} L_i(x, \omega) \cos \theta d\omega$$



### Challenges

- Visibility and blockers
- Varying light distribution
- Complex source geometry

Source: Agrawala, Ramamoorthi, Heirich, Moll, 2000

## Monte Carlo

- Algorithms based on statistical sampling and random numbers
- Coined in the beginning of 1940s. Originally used for neutron transport, nuclear simulations
  - Von Neumann, Ulam, Metropolis, ...
- Canonical example: 1D integral done numerically
  - Choose a set of random points to evaluate function, and then average (expectation or statistical average)

## Monte Carlo Algorithms

### Advantages

- Robust for complex integrals in computer graphics (irregular domains, shadow discontinuities and so on)
- Efficient for high dimensional integrals (common in graphics: time, light source directions, and so on)
- Quite simple to implement
- Work for general scenes, surfaces
- Easy to reason about (but care taken re statistical bias)

### Disadvantages

- Noisy
- Slow (many samples needed for convergence)
- Not used if alternative analytic approaches exist (but those are rare)

## Integration in 1D

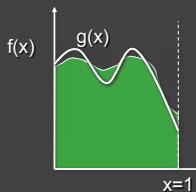
$$\int_0^1 f(x) dx = ?$$



Slide courtesy of Peter Shirley

## We can approximate

$$\int_0^1 f(x) dx \approx \int_0^1 g(x) dx$$



Standard integration methods like trapezoidal rule and Simpsons rule

Advantages:

- Converges fast for **smooth** integrands
- Deterministic

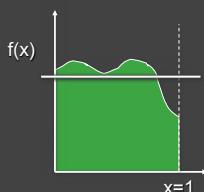
Disadvantages:

- Exponential complexity in many dimensions
- Not rapid convergence for discontinuities

Slide courtesy of Peter Shirley

## Or we can average

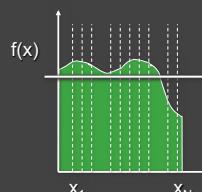
$$\int_0^1 f(x) dx = E(f(x))$$



Slide courtesy of Peter Shirley

## Estimating the average

$$\int_0^1 f(x) dx = \frac{1}{N} \sum_{i=1}^N f(x_i)$$



Monte Carlo methods (random choose samples)

Advantages:

- Robust for discontinuities
- Converges reasonably for large dimensions
- Can handle complex geometry, integrals
- Relatively simple to implement, reason about

Slide courtesy of Peter Shirley

## Other Domains

$$\int_a^b f(x) dx = \frac{b-a}{N} \sum_{i=1}^N f(x_i)$$

Side courtesy of Peter Shirley

## Multidimensional Domains

Same ideas apply for integration over ...

- Pixel areas
- Surfaces
- Projected areas
- Directions
- Camera apertures
- Time
- Paths

$$\int f(x) dx = \frac{1}{N} \sum_{i=1}^N f(x_i)$$

## Random Variables

- Describes possible outcomes of an experiment
- In discrete case, e.g. value of a dice roll [ $x = 1-6$ ]
- Probability  $p$  associated with each  $x$  (1/6 for dice)
- Continuous case is obvious extension

## Expected Value

- Expectation Discrete:  $E(x) = \sum_{i=1}^n p_i x_i$   
Continuous:  $E(x) = \int_0^1 p(x)f(x) dx$
- For Dice example:  

$$E(x) = \sum_{i=1}^6 \frac{1}{6} x_i = \frac{1}{6} (1+2+3+4+5+6) = 3.5$$

## Continuous Probability Distributions

**PDF  $p(x)$**   
 $p(x) \geq 0$

**Uniform**

**CDF  $P(x)$**

$$P(x) = \int_0^x p(x) dx$$

$$P(x) = \Pr(X < x)$$

$$P(1) = 1$$

$$\Pr(\alpha \leq X \leq \beta) = \int_{\alpha}^{\beta} p(x) dx$$

$$= P(\beta) - P(\alpha)$$

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## Sampling Techniques

Problem: how do we generate random points/directions during path tracing?

- Non-rectilinear domains
- Importance (BRDF)
- Stratified

## Generating Random Points

Uniform distribution:

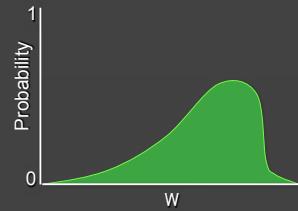
- Use random number generator



## Generating Random Points

Specific probability distribution:

- Function inversion
- Rejection
- Metropolis



## Common Operations

Want to **sample** probability distributions

- Draw samples distributed according to probability
- Useful for integration, picking important regions, etc.

Common distributions

- Disk or circle
- Uniform
- Upper hemisphere for visibility
- Area luminaire
- Complex lighting like an environment map
- Complex reflectance like a BRDF

## Sampling Continuous Distributions

**Cumulative probability distribution function**

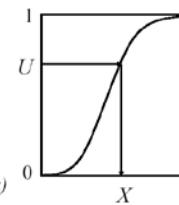
$$P(x) = \Pr(X < x)$$

**Construction of samples**

$$\text{Solve for } X = P^{-1}(U)$$

**Must know:**

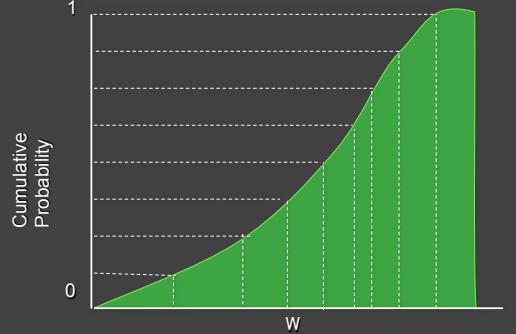
1. The integral of  $p(x)$
2. The inverse function  $P^{-1}(x)$



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## Generating Random Points



## Example: Power Function

**Assume**

$$p(x) = (n+1)x^n$$

$$\int_0^1 x^n dx = \frac{x^{n+1}}{n+1} \Big|_0^1 = \frac{1}{n+1}$$

$$P(x) = x^{n+1}$$

$$X \sim p(x) \Rightarrow X = P^{-1}(U) = \sqrt[n+1]{U}$$

**Trick**

$$Y = \max(U_1, U_2, \dots, U_n, U_{n+1})$$

$$\Pr(Y < x) = \prod_{i=1}^{n+1} \Pr(U_i < x) = x^{n+1}$$

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### Sampling a Circle

$A = \int_0^{2\pi} \int_0^1 r dr d\theta = \int_0^1 r dr \int_0^{2\pi} d\theta = \left( \frac{r^2}{2} \right) \Big|_0^1 \theta \Big|_0^{2\pi} = \pi$   
 $p(r, \theta) dr d\theta = \frac{1}{\pi} r dr d\theta \Rightarrow p(r, \theta) = \frac{r}{\pi}$   
 $p(r, \theta) = p(r)p(\theta)$   
 $p(\theta) = \frac{1}{2\pi}$   
 $P(\theta) = \frac{1}{2\pi} \theta$   
 $p(r) = 2r$   
 $P(r) = r^2$

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### Sampling a Circle

**WRONG  $\neq$  Equi-Areal**

$\theta = 2\pi U_1$

**RIGHT = Equi-Areal**

$\theta = 2\pi U_1$

$r = \sqrt{U_2}$

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### Rejection Sampling

Probability

0 1

W

### Rejection Methods

$I = \int_0^1 f(x) dx$   
 $= \iint_{y < f(x)} dx dy$

**Algorithm**

**Pick**  $U_1$  **and**  $U_2$

**Accept**  $U_1$  **if**  $U_2 < f(U_1)$

**Wasteful?** Efficiency = Area / Area of rectangle

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### Sampling a Circle: Rejection

```

do {
  X=1-2*U1
  Y=1-2*U2
  while( X^2+ Y^2 >1 )

```

May be used to pick random 2D directions

Circle techniques may also be applied to the sphere

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### More formally

<b>Definite integral</b>	$I(f) \equiv \int_0^1 f(x) dx$
<b>Expectation of <math>f</math></b>	$E[f] \equiv \int_0^1 f(x) p(x) dx$
<b>Random variables</b>	$X_i \sim p(x)$ $Y_i = f(X_i)$
<b>Estimator</b>	$F_N = \frac{1}{N} \sum_{i=1}^N Y_i$

### Unbiased Estimator

$$E[F_N] = I(f)$$

$$E[F_N] = E\left[\frac{1}{N} \sum_{i=1}^N Y_i\right]$$

$$= \frac{1}{N} \sum_{i=1}^N E[Y_i] = \frac{1}{N} \sum_{i=1}^N E[f(X_i)]$$

$$= \frac{1}{N} \sum_{i=1}^N \int_0^1 f(x) p(x) dx$$

**Properties**

$$E\left[\sum_i Y_i\right] = \sum_i E[Y_i]$$

$$E[aY] = aE[Y]$$

$$= \frac{1}{N} \sum_{i=1}^N \int_0^1 f(x) dx$$

$$= \int_0^1 f(x) dx$$

Assume uniform probability distribution for now

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### Direct Lighting – Directional Sampling

$$E(x) = \int_{\Omega} L(x, \omega) \cos \theta d\omega$$

Ray intersection  $x^*(x, \omega)$

Sample  $\omega$  uniformly by  $\Omega$

$$Y_i = L(x^*(x, \omega_i), -\omega_i) \cos \theta_i 2\pi$$

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### Direct Lighting – Area Sampling

$$E(x) = \int_{\Omega} L(x, \omega) \cos \theta d\omega = \int_{A'} L_o(x', \omega') V(x, x') \frac{\cos \theta \cos \theta'}{|x - x'|^2} dA'$$

Ray direction  $\omega' = x - x'$

Sample  $x'$  uniformly by  $A'$

$$Y_i = L_o(x'_i, \omega'_i) V(x, x'_i) \frac{\cos \theta \cos \theta'_i}{|x - x'_i|^2} A'$$

$$V(x, x') = \begin{cases} 0 & \text{non-visible} \\ 1 & \text{visible} \end{cases}$$

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### Importance Sampling

Put more samples where  $f(x)$  is bigger

$$\int_{\Omega} f(x) dx = \frac{1}{N} \sum_{i=1}^N Y_i$$

$$Y_i = \frac{f(x_i)}{p(x_i)}$$

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### Importance Sampling

- This is still unbiased

$$E[Y_i] = \int_{\Omega} Y(x)p(x) dx$$

$$= \int_{\Omega} \frac{f(x)}{p(x)} p(x) dx$$

$$= \int_{\Omega} f(x) dx$$

for all N

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### Importance Sampling

- Zero variance if  $p(x) \sim f(x)$

$$p(x) = cf(x)$$

$$Y_i = \frac{f(x_i)}{p(x_i)} = \frac{1}{c}$$

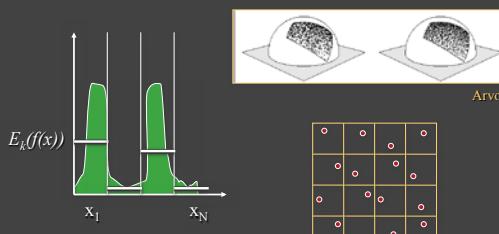
$$Var(Y) = 0$$

Less variance with better importance sampling

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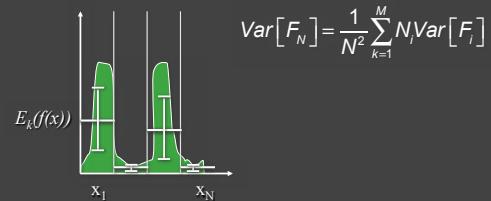
## Stratified Sampling

- Estimate subdomains separately



## Stratified Sampling

- Less overall variance if less variance in subdomains



## More Information

- Veach PhD thesis chapter (linked to from website)
- Course Notes (links from website)
  - Mathematical Models for Computer Graphics*, Stanford, Fall 1997
  - State of the Art in Monte Carlo Methods for Realistic Image Synthesis*, Course 29, SIGGRAPH 2001