

Sampling and Reconstruction of Visual Appearance: From Denoising to View Synthesis

CSE 274 [Fall 2022], Lecture 3

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Motivation: Monte Carlo Rendering

- Key application area for sampling/reconstruction
- Modern methods for denoising now popular
- 1-3 order of magnitude speedups in mature area
- Denoising now standard in production rendering
 - And in real-time, going down to 1spp
- This, next week: Basic background in rendering
 - Reflection and Rendering Equations
 - Monte Carlo Integration
 - Path Tracing (Basic Monte Carlo rendering method)
 - Also the basics of CSE 168 (163)

Sign up (email me) re paper presentations

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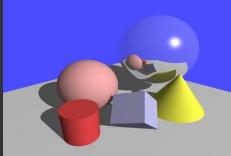
Illumination Models

Local Illumination

- Light directly from light sources to surface
- No shadows (cast shadows are a global effect)

Global Illumination: multiple bounces (indirect light)

- Hard and soft shadows
- Reflections/refractions (already seen in ray tracing)
- Diffuse and glossy interreflections (radiosity, caustics)



Some images courtesy Henrik Wann Jensen

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Caustics

Caustics: Focusing through specular surface



- Major research effort in 80s, 90s till today

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Overview of lecture

- **Theory** for all global illumination methods (ray tracing, *path tracing*, radiosity)
- We derive **Rendering Equation** [Kajiya 86]
 - Major theoretical development in field
 - Unifying framework for all global illumination
 - Introduced Path Tracing: core rendering method
- Discuss existing approaches as special cases

Fairly theoretical lecture (but important). Not well covered in textbooks (though see Eric Veach's thesis). See reading if you are interested.

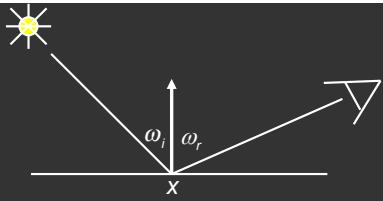
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Outline

- **Reflectance Equation**
- **Global Illumination**
- **Rendering Equation**
- As a general Integral Equation and Operator
- Approximations (Ray Tracing, Radiosity)
- Surface Parameterization (Standard Form)

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Reflection Equation

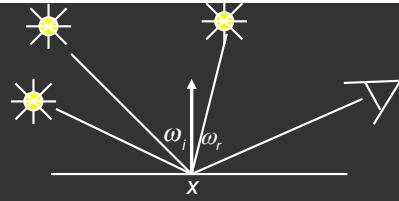


$$L_r(x, \omega_r) = L_e(x, \omega_r) + \sum_i L_i(x, \omega_i) f(x, \omega_i, \omega_r) (\omega_i \cdot n)$$

Reflected Light Emission Incident BRDF Cosine of
(Output Image) (from Light (from Incident angle)
light source) light source)

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Reflection Equation



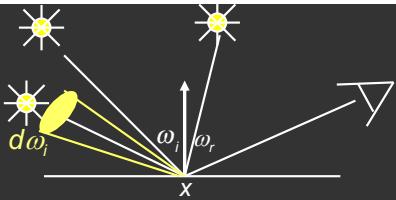
Sum over all light sources

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \sum_i L_i(x, \omega_i) f(x, \omega_i, \omega_r) (\omega_i \cdot n)$$

Reflected Light Emission Incident BRDF Cosine of
(Output Image) (from Light (from Incident angle)
light source) light source)

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Reflection Equation



Replace sum with integral

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_i(x, \omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Reflected Light Emission Incident BRDF Cosine of
(Output Image) (from Light (from Incident angle)
light source) light source)

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Environment Maps

- Light as a function of direction, from entire environment
- Captured by photographing a chrome steel or mirror sphere
- Accurate only for one point, but distant lighting same at other scene locations (typically use only one env. map)



Blinn and Newell 1976, Miller and Hoffman, 1984
Later, Greene 86, Cabral et al. 87

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The Challenge

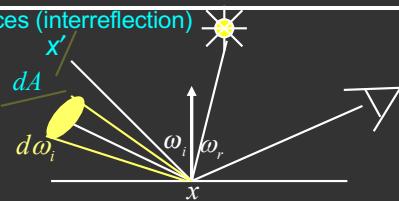
$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_i(x, \omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

- Computing reflectance equation requires knowing the incoming radiance from surfaces
- But determining incoming radiance requires knowing the reflected radiance from surfaces

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Rendering Equation

Surfaces (interreflection)



$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Reflected Light Emission Reflected Light BRDF Cosine of
(Output Image) (from Light UNKNOWN UNKNOWN KNOWN KNOWN
UNKNOWN)

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Outline

- Reflectance Equation (review)
- Global Illumination
- Rendering Equation
- *As a general Integral Equation and Operator*
- *Approximations (Ray Tracing, Radiosity)*
- Surface Parameterization (Standard Form)

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Rendering Equation (Kajiya 86)

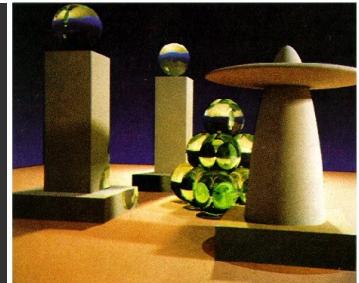


Figure 6. A sample image. All objects are neutral grey. Color on the objects is due to caustics from the green glass balls and color bleeding from the base polygon.

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Rendering Equation as Integral Equation

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Reflected Light (Output Image)	Emission	Reflected Light	BRDF	Cosine of Incident angle
UNKNOWN	KNOWN	UNKNOWN	KNOWN	KNOWN

Is a Fredholm Integral Equation of second kind [extensively studied numerically] with canonical form

$$l(u) = e(u) + \int l(v) K(u, v) dv$$

Kernel of equation

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Linear Operator Theory

- Linear operators act on functions like matrices act on vectors or discrete representations

$$h(u) = (M \circ f)(u) \quad M \text{ is a linear operator.}$$

f and h are functions of u

- Basic linearity relations hold a and b are scalars f and g are functions

$$M \circ (af + bg) = a(M \circ f) + b(M \circ g)$$

- Examples include integration and differentiation

$$(K \circ f)(u) = \int k(u, v) f(v) dv$$

$$(D \circ f)(u) = \frac{\partial f}{\partial u}(u)$$

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Linear Operator Equation

$$l(u) = e(u) + \int l(v) K(u, v) dv$$

Kernel of equation
Light Transport Operator

$$L = E + KL$$

Can be discretized to a simple matrix equation [or system of simultaneous linear equations] (L, E are vectors, K is the light transport matrix)

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Solving the Rendering Equation

- Too hard for analytic solution, numerical methods
- Approximations, that compute different terms, accuracies of the rendering equation
- Two basic approaches are ray tracing, radiosity. More formally, Monte Carlo and Finite Element. Today Monte Carlo path tracing is core rendering method
- Monte Carlo techniques sample light paths, form statistical estimate (example, path tracing)
- Finite Element methods discretize to matrix equation

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Solving the Rendering Equation

- General linear operator solution. Within raytracing:
- General class numerical **Monte Carlo** methods
- Approximate set of all paths of light in scene

$$L = E + KL$$

$$IL - KL = E$$

$$(I - K)L = E$$

$$L = (I - K)^{-1}E$$

Binomial Theorem

$$L = (I + K + K^2 + K^3 + \dots)E$$

$$L = E + KE + K^2E + K^3E + \dots$$

Term n corresponds to n bounces of light

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Ray Tracing

$$L = E + KE + K^2E + K^3E + \dots$$

Emission directly
From light sources

Direct Illumination
on surfaces

Global Illumination
(One bounce indirect)
[Mirrors, Refraction]

(Two bounce indirect)
[Caustics etc]

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Ray Tracing

$$L = E + KE + K^2E + K^3E + \dots$$

Emission directly
From light sources

Direct Illumination
on surfaces

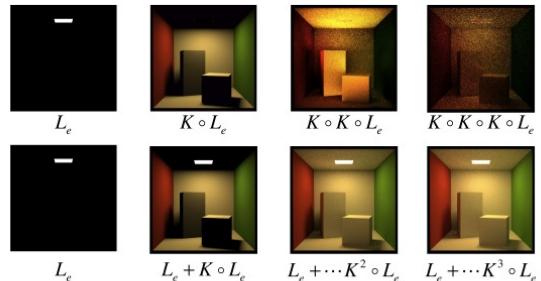
Global Illumination
(One bounce indirect)
[Mirrors, Refraction]

(Two bounce indirect)
[Caustics etc]

OpenGL Shading

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Successive Approximation



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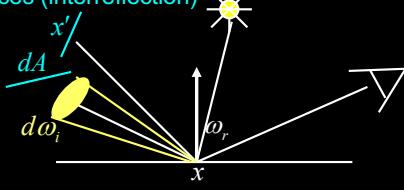
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- Approximations (Ray Tracing, Radiosity)
- **Surface Parameterization (Standard Form)**

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Rendering Equation

Surfaces (interreflection)



$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

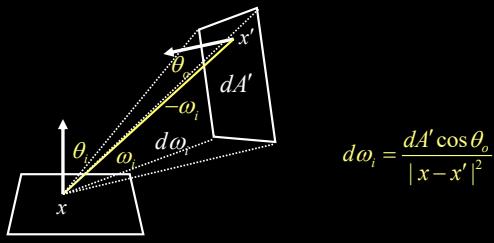
Reflected Light (Output Image)	Emission KNOWN	Reflected Light UNKNOWN	BRDF KNOWN	Cosine of Incident angle KNOWN
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Change of Variables

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Integral over angles sometimes insufficient. Write integral in terms of surface radiance only (change of variables)



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Change of Variables

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Integral over angles sometimes insufficient. Write integral in terms of surface radiance only (change of variables)

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\text{all } x' \text{ visible to } x} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \frac{\cos \theta_i \cos \theta_o}{|x - x'|^2} dA'$$

$$d\omega_i = \frac{dA' \cos \theta_o}{|x - x'|^2}$$

$$G(x, x') = G(x', x) = \frac{\cos \theta_i \cos \theta_o}{|x - x'|^2}$$

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Rendering Equation: Standard Form

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Integral over angles sometimes insufficient. Write integral in terms of surface radiance only (change of variables)

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\text{all } x' \text{ visible to } x} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \frac{\cos \theta_i \cos \theta_o}{|x - x'|^2} dA'$$

Domain integral awkward. Introduce binary visibility fn V

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\text{all surfaces } x'} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) G(x, x') V(x, x') dA'$$

Same as equation 2.52 Cohen Wallace. It swaps primed and unprimed, omits angular args of BRDF, + sign.

Same as equation above 19.3 in Shirley, except he has no emission, slightly diff. notation

$$G(x, x') = G(x', x) = \frac{\cos \theta_i \cos \theta_o}{|x - x'|^2}$$

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Summary

- **Theory** for all global illumination methods (ray tracing, path tracing, radiosity)
- We derive **Rendering Equation** [Kajiya 86]
 - Major theoretical development in field
 - Unifying framework for all global illumination
- Discuss existing approaches as special cases

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Motivation: Monte Carlo Integration

Rendering = integration

- Reflectance equation: Integrate over incident illumination
- Rendering equation: Integral equation

Many sophisticated shading effects involve integrals

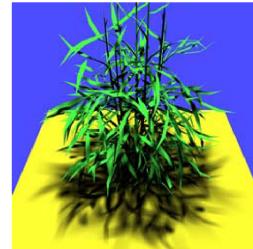
- Antialiasing
- Soft shadows
- Indirect illumination
- Caustics

Most Sampling/Reconstruction treats actual rendering as a black box. But still helpful to know some basics

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Example: Soft Shadows

$$E(x) = \int_{H^2} L_i(x, \omega) \cos \theta d\omega$$



Challenges

- Visibility and blockers
- Varying light distribution
- Complex source geometry

Source: Agrawala, Ramamoorthi, Heirich, Moll, 2000

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Monte Carlo

- Algorithms based on statistical sampling and random numbers
- Coined in the beginning of 1940s. Originally used for neutron transport, nuclear simulations
 - Von Neumann, Ulam, Metropolis, ...
- Canonical example: 1D integral done numerically
 - Choose a set of random points to evaluate function, and then average (expectation or statistical average)

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Monte Carlo Algorithms

Advantages

- Robust for complex integrals in computer graphics (irregular domains, shadow discontinuities and so on)
- Efficient for high dimensional integrals (common in graphics: time, light source directions, and so on)
- Quite simple to implement
- Work for general scenes, surfaces
- Easy to reason about (but care taken re statistical bias)

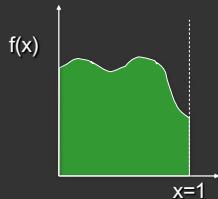
Disadvantages

- Noisy
- Slow (many samples needed for convergence)
- Not used if alternative analytic approaches exist (but those are rare)

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Integration in 1D

$$\int_0^1 f(x) dx = ?$$

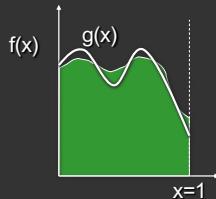


Slide courtesy of Peter Shirley

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We can approximate

$$\int_0^1 f(x) dx \approx \int_0^1 g(x) dx$$



Standard integration methods like trapezoidal rule and Simpsons rule

Advantages:

- Converges fast for **smooth** integrands
- Deterministic

Disadvantages:

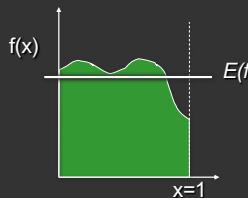
- Exponential complexity in many dimensions
- Not rapid convergence for discontinuities

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Or we can average

$$\int_0^1 f(x) dx = E(f(x))$$

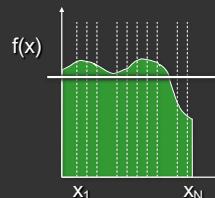


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Estimating the average

$$\int_0^1 f(x) dx = \frac{1}{N} \sum_{i=1}^N f(x_i)$$



Monte Carlo methods (random choose samples)

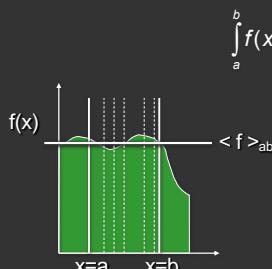
Advantages:

- Robust for discontinuities
- Converges reasonably for large dimensions
- Can handle complex geometry, integrals
- Relatively simple to implement, reason about

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Other Domains



$$\int_a^b f(x) dx = \frac{b-a}{N} \sum_{i=1}^N f(x_i)$$

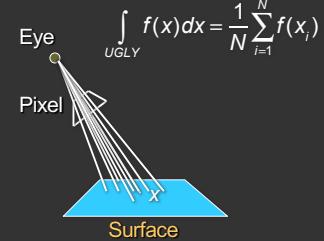
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Multidimensional Domains

Same ideas apply for integration over ...

- Pixel areas
- Surfaces
- Projected areas
- Directions
- Camera apertures
- Time
- Paths



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Random Variables

- Describes possible outcomes of an experiment
- In discrete case, e.g. value of a dice roll [x = 1-6]
- Probability p associated with each x (1/6 for dice)
- Continuous case is obvious extension

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Expected Value

- Expectation Discrete: $E(f) = \sum_{i=1}^n p_i f(x_i)$
- Continuous: $E(f) = \int_0^1 p(x) f(x) dx$
- For Dice example:

$$E(x) = \sum_{i=1}^6 \frac{1}{6} x_i = \frac{1}{6} (1+2+3+4+5+6) = 3.5$$

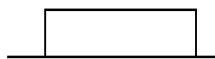
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Continuous Probability Distributions

PDF $p(x)$

$$p(x) \geq 0$$

Uniform



CDF $P(x)$

$$P(x) = \int_0^x p(x) dx$$

$$P(x) = \Pr(X < x)$$

$$P(1) = 1$$

$$\Pr(\alpha \leq X \leq \beta) = \int_{\alpha}^{\beta} p(x) dx$$

$$= P(\beta) - P(\alpha)$$

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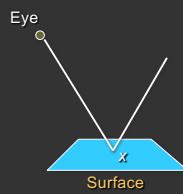
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Sampling Techniques

Problem: how do we generate random points/directions during path tracing?

- Non-rectilinear domains
- Importance (BRDF)
- Stratified



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Generating Random Points

Uniform distribution:

- Use random number generator

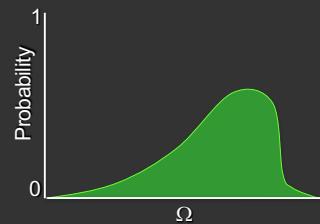


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Generating Random Points

Specific probability distribution:

- Function inversion
- Rejection
- Metropolis



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Common Operations

Want to **sample** probability distributions

- Draw samples distributed according to probability
- Useful for integration, picking important regions, etc.

Common distributions

- Disk or circle
- Uniform
- Upper hemisphere for visibility
- Area luminaire
- Complex lighting like an environment map
- Complex reflectance like a BRDF

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Sampling Continuous Distributions

Cumulative probability distribution function

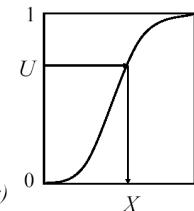
$$P(x) = \Pr(X < x)$$

Construction of samples

Solve for $X = P^{-1}(U)$

Must know:

1. **The integral of $p(x)$**
2. **The inverse function $P^{-1}(x)$**

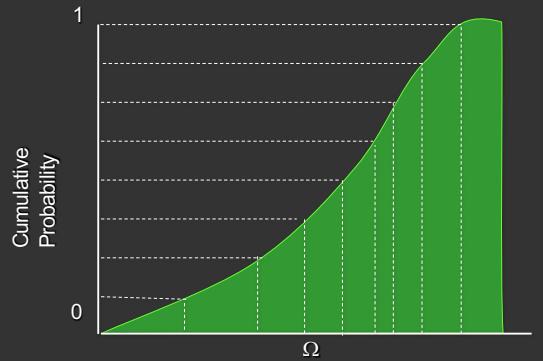


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Generating Random Points



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Example: Power Function

Assume

$$p(x) = (n+1)x^n$$

$$P(x) = x^{n+1}$$

$$X \sim p(x) \Rightarrow X = P^{-1}(U) = \sqrt[n+1]{U}$$

$$\int_0^1 x^n dx = \frac{x^{n+1}}{n+1} \Big|_0^1 = \frac{1}{n+1}$$

Trick

$$Y = \max(U_1, U_2, \dots, U_n, U_{n+1})$$

$$\Pr(Y < x) = \prod_{i=1}^{n+1} \Pr(U_i < x) = x^{n+1}$$

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Sampling a Circle

$$A = \int_0^{2\pi} \int_0^1 r dr d\theta = \int_0^1 r dr \int_0^{2\pi} d\theta = \left(\frac{r^2}{2} \right) \Big|_0^{2\pi} = \pi$$

$$p(r, \theta) dr d\theta = \frac{1}{\pi} r dr d\theta \Rightarrow p(r, \theta) = \frac{r}{\pi}$$

$$p(r, \theta) = p(r)p(\theta)$$

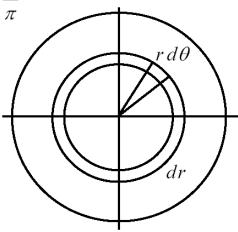
$$p(\theta) = \frac{1}{2\pi}$$

$$P(\theta) = \frac{1}{2\pi} \theta$$

$$p(r) = 2r$$

$$P(r) = r^2$$

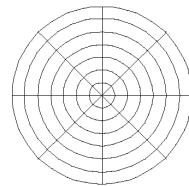
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Sampling a Circle

WRONG \neq Equi-Areal

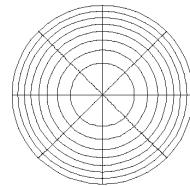


$$\theta = 2\pi U_1$$

$$r = U_2$$

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RIGHT = Equi-Areal



$$\theta = 2\pi U_1$$

$$r = \sqrt{U_2}$$

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Rejection Sampling



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Rejection Methods

$$I = \int_0^1 f(x) dx \\ = \iint_{y < f(x)} dx dy$$

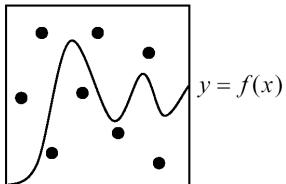
Algorithm

Pick U_1 and U_2

Accept U_1 if $U_2 < f(U_1)$

Wasteful? Efficiency = Area / Area of rectangle

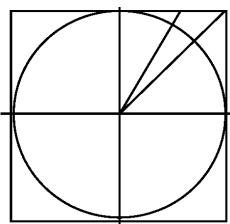
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Sampling a Circle: Rejection



```
do {
  X=1-2*U1
  Y=1-2*U2
  while( X^2+ Y^2 >1 )
```

May be used to pick random 2D directions

Circle techniques may also be applied to the sphere

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More formally

Definite integral

$$I(f) \equiv \int_0^1 f(x) dx$$

Expectation of f

$$E[f] \equiv \int_0^1 f(x) p(x) dx$$

Random variables

$$X_i \sim p(x)$$

$$Y_i = f(X_i)$$

Estimator

$$F_N = \frac{1}{N} \sum_{i=1}^N Y_i$$

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Unbiased Estimator

$$E[F_N] = I(f)$$

$$\begin{aligned} E[F_N] &= E\left[\frac{1}{N} \sum_{i=1}^N Y_i\right] \\ &= \frac{1}{N} \sum_{i=1}^N E[Y_i] = \frac{1}{N} \sum_{i=1}^N E[f(X_i)] \\ &= \frac{1}{N} \sum_{i=1}^N \int_0^1 f(x) p(x) dx \\ &= \frac{1}{N} \sum_{i=1}^N \int_0^1 f(x) dx \\ &= \int_0^1 f(x) dx \end{aligned}$$

Properties

$$\begin{aligned} E\left[\sum_i Y_i\right] &= \sum_i E[Y_i] \\ E[aY] &= aE[Y] \end{aligned}$$

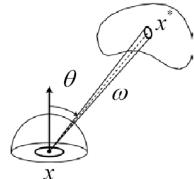
Assume uniform probability distribution for now

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Direct Lighting – Directional Sampling

$$E(x) = \int_{\Omega} L(x, \omega) \cos \theta d\omega$$



Ray intersection $x^*(x, \omega)$

Sample ω uniformly by Ω

$$Y_i = L(x^*(x, \omega_i), -\omega_i) \cos \theta / 2\pi$$

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Direct Lighting – Area Sampling

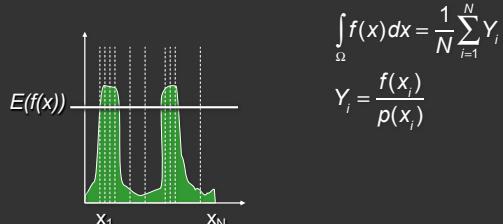
$$\begin{aligned} E(x) &= \int_{\Omega} L_i(x, \omega) \cos \theta d\omega = \int_{A'} L_o(x', \omega') V(x, x') \frac{\cos \theta \cos \theta'}{|x - x'|^2} dA' \\ &\text{Ray direction } \omega' = x - x' \\ &\text{Sample } x' \text{ uniformly by } A' \\ &Y_i = L_o(x'_i, \omega'_i) V(x, x'_i) \frac{\cos \theta \cos \theta'_i}{|x - x'_i|^2} A \\ &V(x, x') = \begin{cases} 0 & \text{visible} \\ 1 & \text{visible} \end{cases} \end{aligned}$$

CS348B Lecture 6

Pat Hanrahan, Spring 2004

Importance Sampling

Put more samples where $f(x)$ is bigger

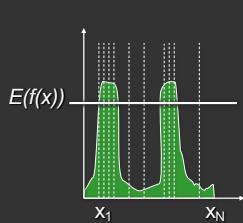


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Importance Sampling

- This is still unbiased



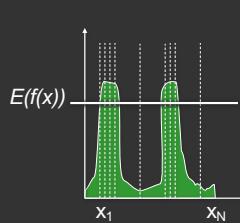
$$\begin{aligned} E[Y_i] &= \int_{\Omega} Y(x) p(x) dx \\ &= \int_{\Omega} \frac{f(x)}{p(x)} p(x) dx \\ &= \int_{\Omega} f(x) dx \end{aligned}$$

for all N

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Importance Sampling

- Zero variance if $p(x) \sim f(x)$



$$p(x) = cf(x)$$

$$Y_i = \frac{f(x_i)}{p(x_i)} = \frac{1}{c}$$

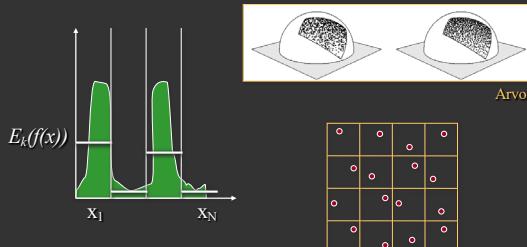
$$Var(Y) = 0$$

Less variance with better importance sampling

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Stratified Sampling

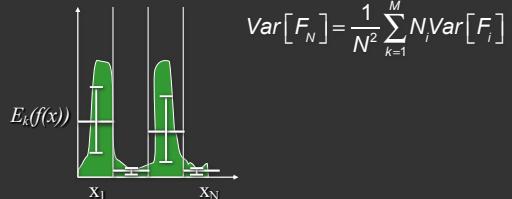
- Estimate subdomains separately



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Stratified Sampling

- Less overall variance if less variance in subdomains



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More Information

- Veach PhD thesis chapter (linked to from website)
- Course Notes (links from website)
 - Mathematical Models for Computer Graphics*, Stanford, Fall 1997
 - State of the Art in Monte Carlo Methods for Realistic Image Synthesis*, Course 29, SIGGRAPH 2001

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