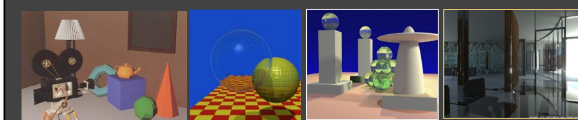
Computer Graphics II: Rendering

CSE 168 [Spr 20], Lecture 17: Image-Based Rendering
Ravi Ramamoorthi

http://viscomp.ucsd.edu/classes/cse168/sp20



To Do

- Project proposals due tomorrow (May 27)
- Final Projects due Jun 9
- PLEASE FILL OUT CAPE EVALUATIONS!!
- KEEP WORKING HARD

Motivation for Lecture

- Image-Based Rendering major new idea in graphics in past 25 years
- Many of the rendering methods, especially precomputed techniques borrow from it
- And many methods use measured data
- Also, images are an important source for rendering
- Sampled data rapidly becoming popular
- Core IBR problem of view synthesis/light fields renewed popularity (VR other applications)

Traditional Modeling and Rendering

SIGGRAPH

Model

User Input (texture maps, survey data) → Modeling → Geometry, Reflectance, Light sources → Rendering → Images

For Photorealism:

Modeling is Hard **Rendering is Slow**

Next few slides courtesy Paul Debevec; SIGGRAPH 99 course notes

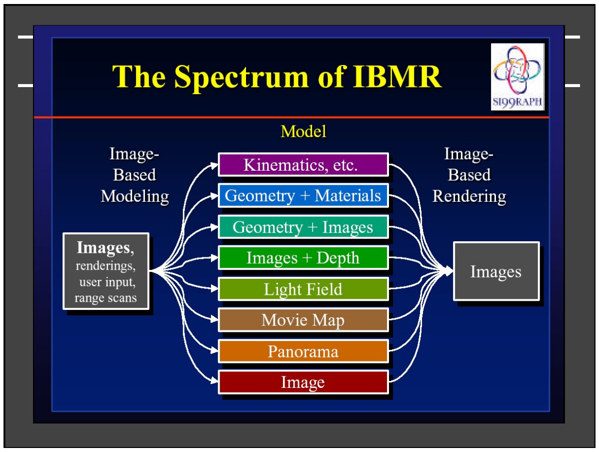
Can we model and render this?

What do we want to do with the model?

Image-Based Modeling and Rendering

SIGGRAPH

Images, user input, range scans → Image-Based Modeling → Model → Image-Based Rendering → Images



IBR: Pros and Cons

- Advantages
  - Easy to capture images: photorealistic by definition
  - Simple, universal representation
  - Often bypass geometry estimation?
  - Independent of scene complexity?
- Disadvantages
  - WYSIWYG but also WYSIAYG
  - Explosion of data as flexibility increased
  - Often discards intrinsic structure of model?
- Today, IBR-type methods also often used in synthetic rendering (e.g. real-time rendering PRT)
  - General concept of data-driven graphics, appearance
  - Also, data-driven geometry, animation, simulation
  - Spawned light field cameras for image capture

Image-Based Models: What do they allow?

Model	Movement	Geometry	Lighting
Geometry + Materials	Continuous	Global	Dynamic
Geometry + Images	Continuous	Global	Fixed
Images + Depth	Continuous	Local	Fixed
Light Field	Continuous	None	Fixed
Movie Map	Discrete	None	Fixed
Panorama	Rotation	None	Fixed
Image	None	None	Fixed

IBR: A brief history

- Texture maps, bump maps, environment maps [70s]
- Poggio MIT 90s: Faces, image-based analysis/synthesis
- Mid-Late 90s
  - Chen and Williams 93, View Interpolation [Images+depth]
  - Chen 95 Quicktime VR [Images from many viewpoints]
  - McMillan and Bishop 95 Plenoptic Modeling [Images w disparity]
  - Gortler et al, Levoy and Hanrahan 96 Light Fields [4D]
  - Shade et al. 98 Layered Depth Images [2.5D]
  - Debevec et al. 00 Reflectance Field [4D]
  - Inverse rendering (Marschner,Sato,Yu,Boivin,…)
- Today: IBR hasn't replaced conventional rendering, but has brought sampled and data-driven representations to graphics

Game #1: increase the dimensionality

2D rgb	texture
2D rgbz	range image
2.5D rgbαz	layered depth images
4D rgb	light field / Lumigraph
4D rgbz	array of range images
4.5D rgbαz	layered light fields

Game #2: replace the quantity represented

4D rgb — light field / Lumigraph
$\{u, v, s, t\}$

5D rgb — plenoptic function
$\{x, y, z\} \times \{\theta, \varphi\}$

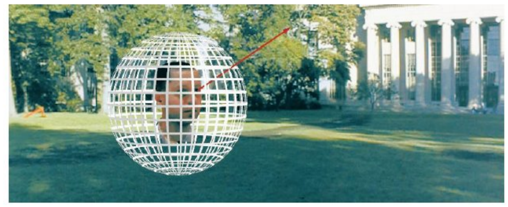
6D ρ — free-space BRDF field
$\{u, v, s, t\} \times \{\theta_i, \varphi_i\}$

7D ρ — BRDF volume
$\{x, y, z\} \times \{\theta_i, \varphi_i, \theta_r, \varphi_r\}$

Outline

- Overview of IBR
- Basic approaches
  - *Image Warping*
    - *[2D + depth. Requires correspondence/disparity]*
  - Light Fields [4D]
  - Survey of some early work

Images as a Collection of Rays



An image is a subset of the rays seen from a given point
- this "space" of rays occupies two dimensions

Warping slides courtesy Leonard McMillan, SIGGRAPH 99 course notes

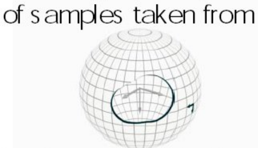
The Plenoptic Function

✔ The set of rays seen from all points ...

$$p = P(\theta, \phi, x, y, z, \lambda, t)$$

Image-based rendering is about

...reconstructing a plenoptic function from a set of samples taken from it.

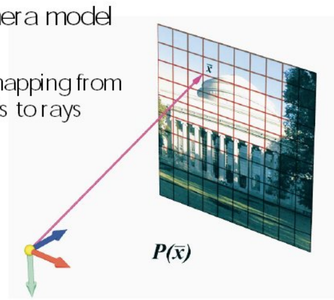


✔ Ignoring time, and selecting a discrete set of wavelengths gives a 5-D plenoptic function

Where to Begin?

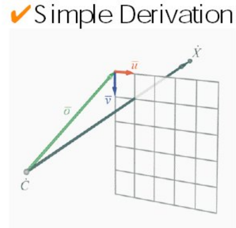
✔ Pinhole camera model

- Defines a mapping from image points to rays in space



Mapping from Rays to Points

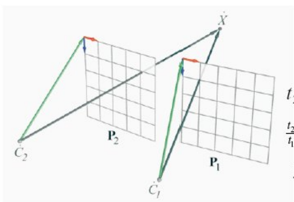
✔ Simple Derivation



$$P = \begin{bmatrix} u_x & v_x & o_x \\ u_y & v_y & o_y \\ u_z & v_z & o_z \end{bmatrix}$$

$$\dot{X} = \dot{C} + t\,P\,\vec{x}$$

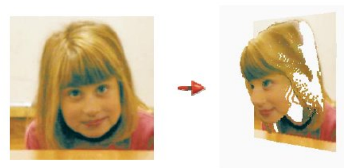
Correspondence



$$\dot{C}_2 + t_2 P_2 \vec{x}_2 = \dot{C}_1 + t_1 P_1 \vec{x}_1$$
$$t_2 P_2 \vec{x}_2 = \dot{C}_1 - \dot{C}_2 + t_1 P_1 \vec{x}_1$$
$$t_2 \vec{x}_2 = P_2^{-1}(\dot{C}_1 - \dot{C}_2) + t_1 P_2^{-1} P_1 \vec{x}_1$$
$$\frac{t_2}{t_1}\vec{x}_2 = \frac{1}{t_1} P_2^{-1}(\dot{C}_1 - \dot{C}_2) + P_2^{-1} P_1 \vec{x}_1$$
$$\vec{x}_2 \doteq \underbrace{\frac{1}{t_1}}_{\delta} \underbrace{P_2^{-1}(\dot{C}_1 - \dot{C}_2)}_{\vec{e}_{21}} + \underbrace{P_2^{-1} P_1}_{H_{21}} \vec{x}_1$$

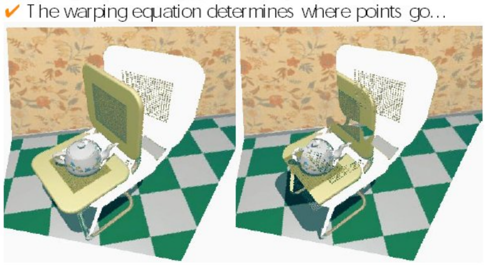
Warping in Action

- A 3D Warp



Visibility

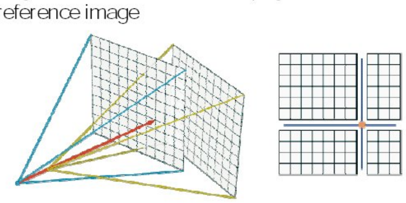
- The warping equation determines where points go…



… but that is not sufficient

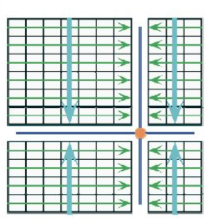
Partition Reference Image

- Project the *desired* center-of-projection onto the reference image



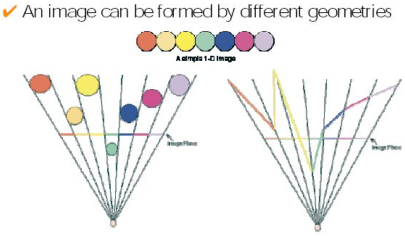
Enumeration

- Drawing toward the projected point guarantees an *occlusion compatible* ordering
- Ordering is consistent with a painter's algorithm
- Independent of the scene's contents
- Easily generalized to other viewing surfaces
- No auxiliary information required



Reconstruction

- Typical images are discrete, not continuous
- An image can be formed by different geometries



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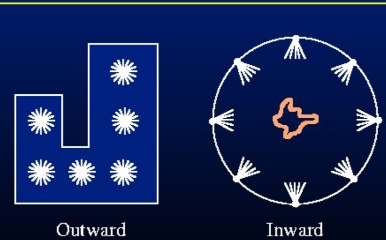
  - *Light Fields [4D]*
  - Survey of some early work

Light Field Rendering

Marc Levoy   *Pat Hanrahan*

Computer Science Department
Stanford University

Apple's QuickTime VR



Generating New Views

Problem: fixed vantage point/center

One Solution: view interpolation

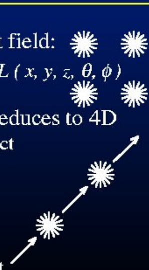
- Interpolating between range images (Chen and Willams, 1993)
- Correspondences and epipolar analysis (McMillan and Bishop, 1995)

-> Requires depths or correspondences:
  must be extracted from acquired imagery
  relatively expensive and error-prone morph

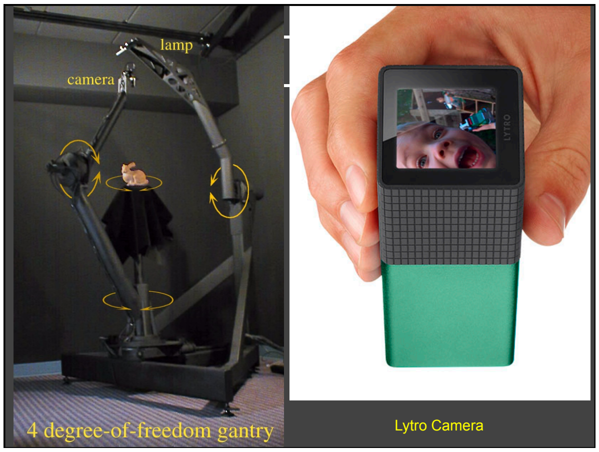
Light Fields

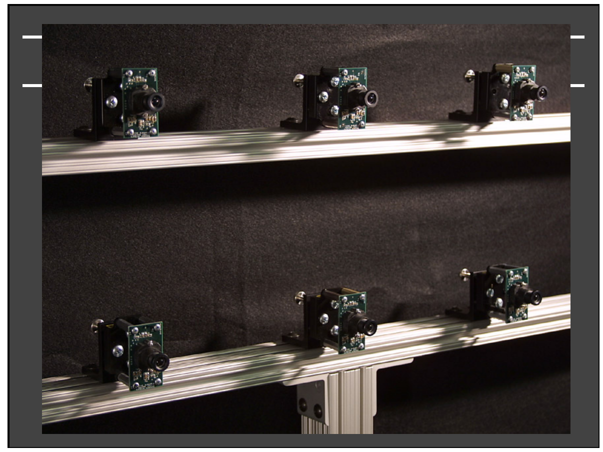
Gershun's and Moon's idea of a light field:
Radiance as a function of a ray or line: $L(x, y, z, \theta, \phi)$

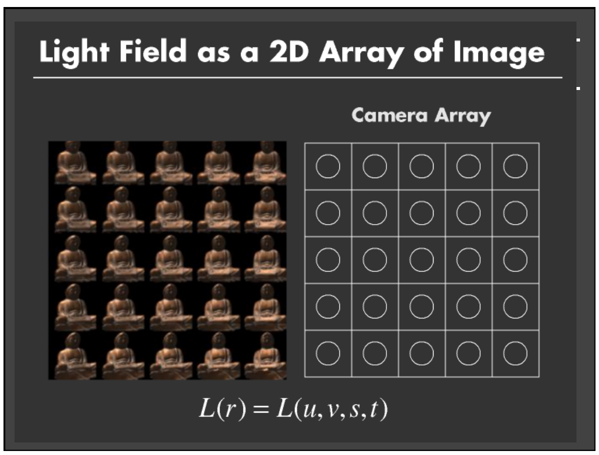
- In "free space" (no occluders) 5D reduces to 4D
  - Exterior of the convex hull of an object
  - Interior of an environment
- Images are 2D slices
  - Insert acquired imagery
  - Extract image from a given viewpoint

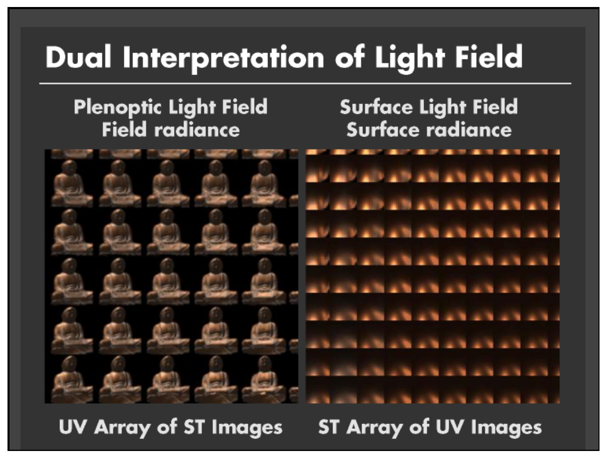


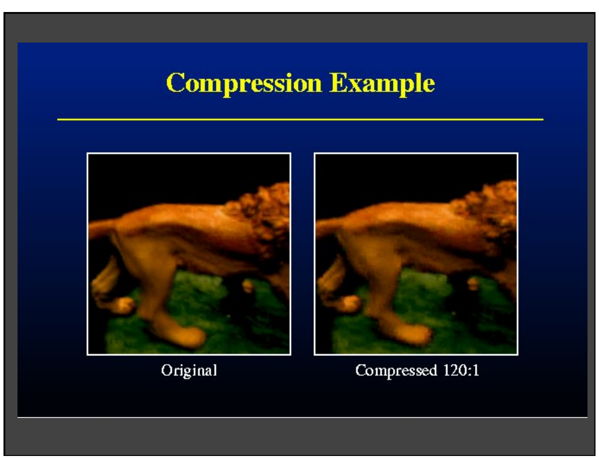
4D Light Field











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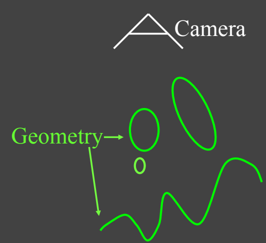
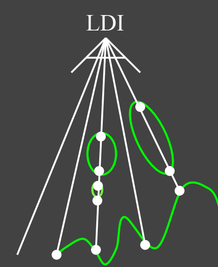
Layered Depth Images [Shade 98]



Slide from Agrawala, Ramamoorthi, Heirich, Moll, SIGGRAPH 2000

Layered Depth Images [Shade 98]



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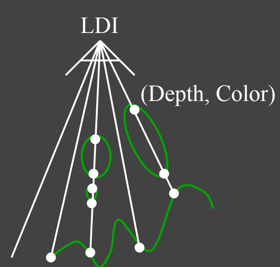


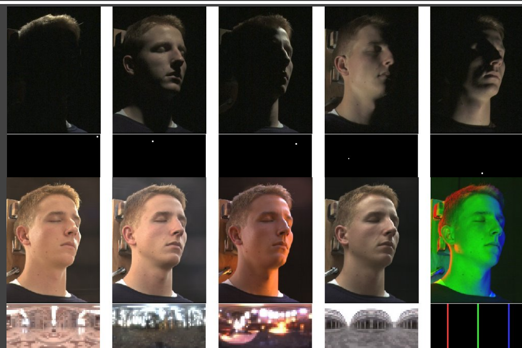
Surface Light Fields

- Miller 98, Nishino 99, Wood 00
- Reflected light field (lumisphere) on surface
- Explicit geometry as against light fields. Easier compress

Acquiring Reflectance Field of Human Face [Debevec et al. SIGGRAPH 00]

Illuminate subject from many incident directions

Example Images



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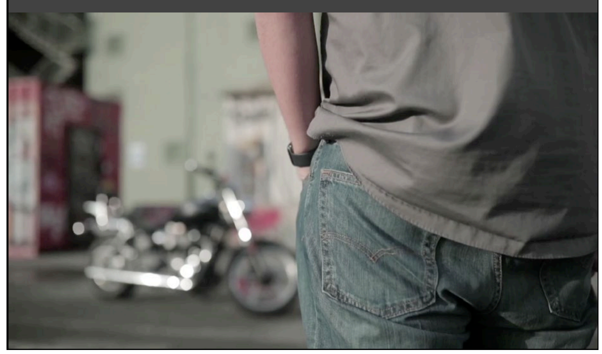
  - *Survey of some recent work*
    - *Sampled data representations*

Conclusion (my views)

- IBR initially spurred great excitement: revolutionize pipeline
- But, IBR in pure form not really practical
  - WYSIAYG
  - Explosion as increase dimensions (8D transfer function)
  - Good compression, flexibility needs at least implicit geometry/BRDF
- Real future is sampled representations, data-driven method
  - Acquire (synthetic or real) data
  - Good representations for interpolation, fast rendering
  - Much of visual appearance, graphics moving in this direction
- Understand from Signal-Processing Viewpoint
  - Sampling rates, reconstruction filters
  - Factored representations, Fourier analysis
- Light Fields fundamental in many ways, including imaging
  - *Renewed interest in view synthesis (Mildenhall et al. SIGGRAPH 19)*

Virtual Experiences of Real-World Scenes



Input Images

Output Light Field


Local Light Field Fusion