

## Computer Graphics

CSE 167 [Win 24], Lecture 9: Curves 1

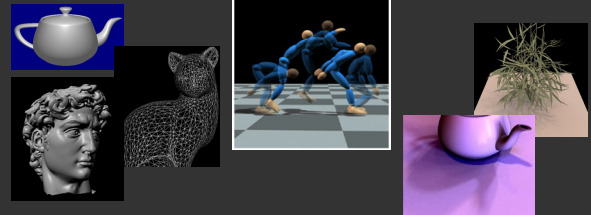
Ravi Ramamoorthi

<http://viscomp.ucsd.edu/classes/cse167/wi24>

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## Course Outline

- 3D Graphics Pipeline



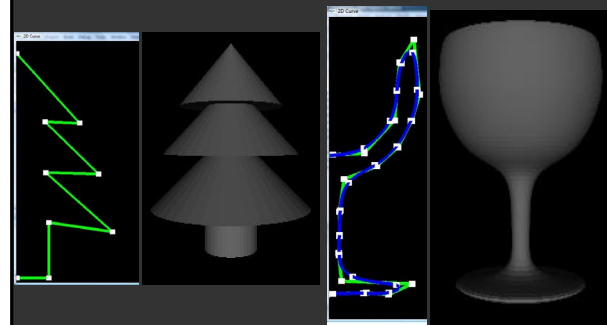
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## Graphics Pipeline

- In HW 1, HW 2, draw, shade objects
- But how to define geometry of objects?
- How to define, edit shape of teapot?
- We discuss *modeling* with spline curves
  - Demo of HW 3 solution
- Homework submission (Feb 28)
  - After midterm, but please start on it before
  - Not on UCSD Online, link
  - See piazza for password (and code grade only)

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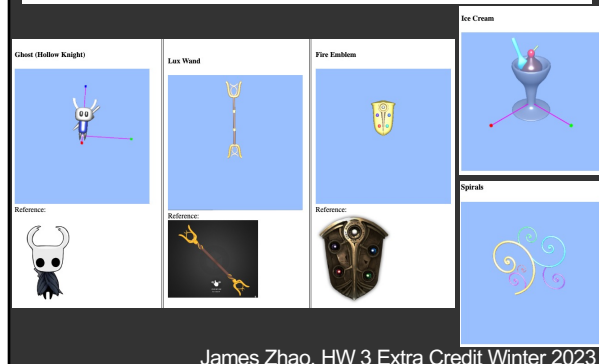
## Curves for Modeling



Rachel Shiner, Final Project Spring 2010

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## Curves for Modeling



James Zhao, HW 3 Extra Credit Winter 2023

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## Motivation

- How do we model complex shapes?
  - In this course, only 2D curves, but can be used to create interesting 3D shapes by surface of revolution, lofting etc
- Techniques known as spline curves
- This unit is about mathematics required to draw these spline curves, as in HW 3
- History: From using computer modeling to define car bodies in auto-manufacturing. Pioneers are Pierre Bezier (Renault), de Casteljau (Citroen)

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## Splines Video

- <https://www.youtube.com/watch?v=YMI25iCCRew&list=PLWfDJ5nla8UpwShx-lzLJqcp575fKpsSO&index=13>
- Steve Seitz UW 5 minute videos (only first 2.5min)
- Can watch other splines videos on channel, but don't match the math as taught in this class.

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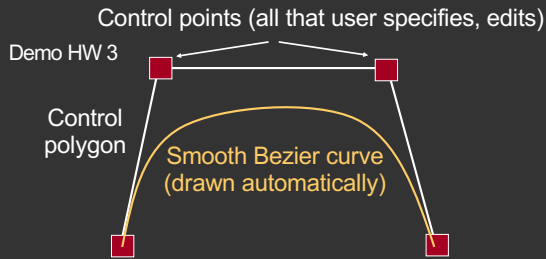
## Outline of Unit

- *Bezier curves*
- deCasteljau algorithm, explicit form, matrix form
- Polar form labeling (next time)
- B-spline curves (next time)
- Not well covered in textbooks (especially as taught here). Main reference will be lecture notes. If you do want a printed ref, handouts from CAGD, Seidel

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## Bezier Curve (with HW3 demo)

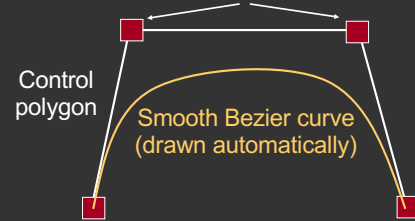
- *Motivation: Draw a smooth intuitive curve (or surface) given few key user-specified control points*



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## Bezier Curve: (Desirable) properties

- Interpolates, is tangent to end points
  - Curve within convex hull of control polygon
- Control points (all that user specifies, edits)



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## Survey

- Anonymous, know how things are going
- Will try to use it to improve course

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## Issues for Bezier Curves

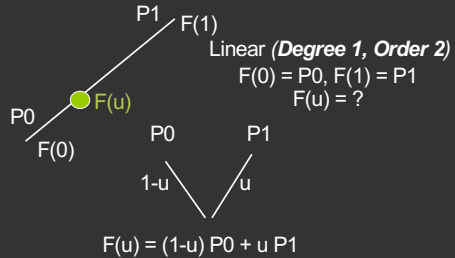
Main question: Given control points and constraints (interpolation, tangent), how to construct curve?

- *Algorithmic: deCasteljau algorithm*
- Explicit: Bernstein-Bezier polynomial basis
- 4x4 matrix for cubics
- Properties: Advantages and Disadvantages

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### deCasteljau: Linear Bezier Curve

- Just a simple linear combination or interpolation (easy to code up, very numerically stable)



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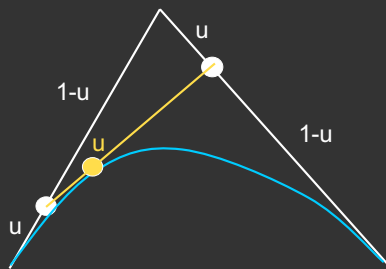
### deCasteljau: Quadratic Bezier Curve



$$F(u) = (1-u)^2 P_0 + 2u(1-u) P_1 + u^2 P_2$$

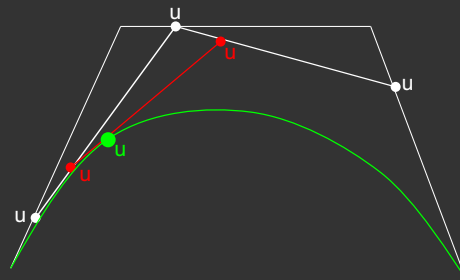
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### Geometric interpretation: Quadratic



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### Geometric Interpretation: Cubic



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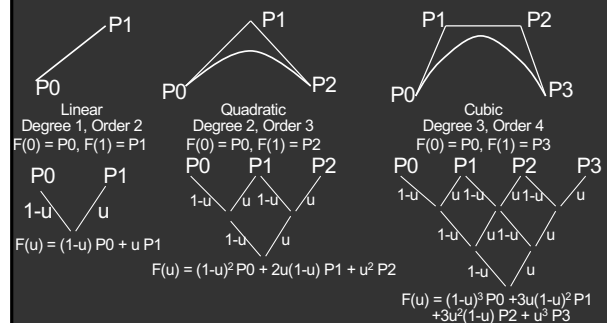
### deCasteljau: Cubic Bezier Curve



$$F(u) = (1-u)^3 P_0 + 3u(1-u)^2 P_1 + 3u^2(1-u) P_2 + u^3 P_3$$

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### Summary: deCasteljau Algorithm



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## DeCasteljau Implementation

Input: Control points  $C_i$  with  $0 \leq i \leq n$  where  $n$  is the degree.  
Output:  $f(u)$  where  $u$  is the parameter for evaluation

```

1 for (level = n ; level >= 0 ; level --) {
2   if (level == n) { // Initial control points
3     for (i = 0 ; i <= n ; i++) p_i^level = C_i ; continue ; }
4   for (i = 0 ; i < level ; i++)
5     p_i^level = (1-u) * p_i^level+1 + u * p_{i+1}^level+1 ;
6 }
7 f(u) = p_0^0

```

- Can be optimized to do without auxiliary storage

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## Summary of HW3 Implementation

Bezier (Bezier2 and Bspline discussed next time)

- Arbitrary degree curve (number of control points)
- Break curve into detail segments. Line segments for these
- Evaluate curve at locations  $0, 1/\text{detail}, 2/\text{detail}, \dots, 1$
- Evaluation done using deCasteljau
- Key implementation: deCasteljau for arbitrary degree
  - Is anyone confused? About handling arbitrary degree?
- Can also use alternative formula if you want
  - Explicit Bernstein-Bezier polynomial form (next)
- Questions?

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## Issues for Bezier Curves

Main question: Given control points and constraints (interpolation, tangent), how to construct curve?

- Algorithmic: deCasteljau algorithm
- Explicit: Bernstein-Bezier polynomial basis
- 4x4 matrix for cubics
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## Recap formulae

- Linear combination of basis functions
- Linear:  $F(u) = P_0(1-u) + P_1u$   
 Quadratic:  $F(u) = P_0(1-u)^2 + P_1[2u(1-u)] + P_2u^2$   
 Cubic:  $F(u) = P_0(1-u)^3 + P_1[3u(1-u)^2] + P_2[3u^2(1-u)] + P_3u^3$
- Degree  $n$ :  $F(u) = \sum_k P_k B_k^n(u)$   
 $B_k^n(u)$  are Bernstein-Bezier polynomials
- Explicit form for basis functions? Guess it?

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- Linear combination of basis functions
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 $B_k^n(u)$  are Bernstein-Bezier polynomials
- Explicit form for basis functions? Guess it?
  - Binomial coefficients in  $[(1-u)+u]^n$**

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## Summary of Explicit Form

- Linear:  $F(u) = P_0(1-u) + P_1u$   
 Quadratic:  $F(u) = P_0(1-u)^2 + P_1[2u(1-u)] + P_2u^2$   
 Cubic:  $F(u) = P_0(1-u)^3 + P_1[3u(1-u)^2] + P_2[3u^2(1-u)] + P_3u^3$
- Degree  $n$ :  $F(u) = \sum_k P_k B_k^n(u)$   
 $B_k^n(u)$  are Bernstein-Bezier polynomials

$$B_k^n(u) = \frac{n!}{k!(n-k)!} (1-u)^{n-k} u^k$$

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### Issues for Bezier Curves

Main question: Given control points and constraints (interpolation, tangent), how to construct curve?

- Algorithmic: deCasteljau algorithm
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- 4x4 matrix for cubics
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### Cubic 4x4 Matrix (derive)

$$F(u) = P_0(1-u)^3 + P_1[3u(1-u)^2] + P_2[3u^2(1-u)] + P_3u^3$$

$$= \begin{pmatrix} u^3 & u^2 & u & 1 \end{pmatrix} \begin{pmatrix} M = ? \end{pmatrix} \begin{pmatrix} P_0 \\ P_1 \\ P_2 \\ P_3 \end{pmatrix}$$

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### Cubic 4x4 Matrix (derive)

$$F(u) = P_0(1-u)^3 + P_1[3u(1-u)^2] + P_2[3u^2(1-u)] + P_3u^3$$

$$= \begin{pmatrix} u^3 & u^2 & u & 1 \end{pmatrix} \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} P_0 \\ P_1 \\ P_2 \\ P_3 \end{pmatrix}$$

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### Issues for Bezier Curves

Main question: Given control points and constraints (interpolation, tangent), how to construct curve?

- Algorithmic: deCasteljau algorithm
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### Properties (brief discussion)

- Demo of HW 3
- Interpolation: End-points, but approximates others
- Single piece, moving one point affects whole curve (no local control as in B-splines later)
- Invariant to translations, rotations, scales etc. That is, translating all control points translates entire curve
- Easily subdivided into parts for drawing (next lecture): Hence, Bezier curves easiest for drawing

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