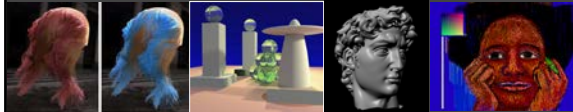


Advanced Computer Graphics

CSE 163 [Spring 2018], Lecture 17

Ravi Ramamoorthi

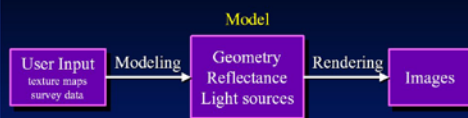
<http://www.cs.ucsd.edu/~ravr>



Motivation for Lecture

- Image-Based Rendering major new idea in graphics in past 20 years
- Many of the rendering methods, especially precomputed techniques borrow from it
- And many methods use measured data
- Also, images are an important source for rendering
- Sampled data rapidly becoming popular

Traditional Modeling and Rendering



For Photorealism:

Modeling is Hard

Rendering is Slow

Next few slides courtesy Paul Debevec; SIGGRAPH 99 course notes



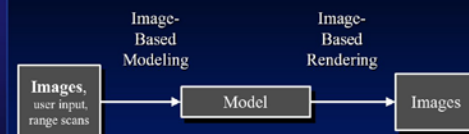
Can we model and render this?

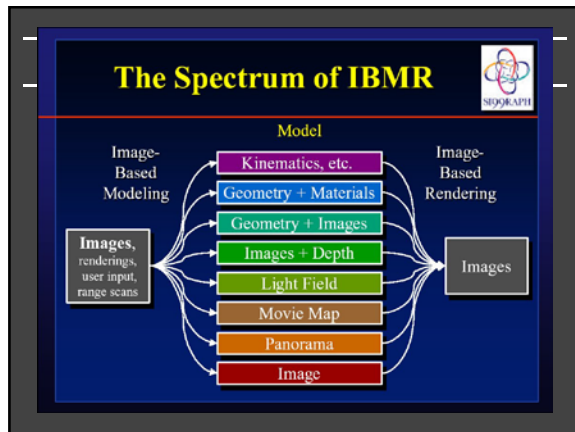
What do we want to do with the model?

To Do

- Assignment 3 milestone due Jun 1
 - Upload on TritonEd
 - If unusual, send to both instructor and TA
 - 1-2 page PDF or website
 - What you have done so far (at least one image)
 - 1-2 para proposal of what you hope to accomplish
 - We may say ok or schedule time to meet, discuss
 - Talk to us if any difficulty finding project
 - Assignment gives some well specified, loose, other options; you can do something else too
- Please fill out CAPE evaluations now
- HW 2 videos

Image-Based Modeling and Rendering





- ## IBR: Pros and Cons
- Advantages
 - Easy to capture images: photorealistic by definition
 - Simple, universal representation
 - Often bypass geometry estimation?
 - Independent of scene complexity?
 - Disadvantages
 - WYSIWYG but also WYSIAYG
 - Explosion of data as flexibility increased
 - Often discards intrinsic structure of model?
 - Today, IBR-type methods also often used in synthetic rendering (e.g. real-time rendering PRT)
 - General concept of data-driven graphics, appearance
 - Also, data-driven geometry, animation, simulation
 - Spawned light field cameras for image capture

Image-Based Models: What do they allow?

Model	Movement	Geometry	Lighting
Geometry + Materials	Continuous	Global	Dynamic
Geometry + Images	Continuous	Global	Fixed
Images + Depth	Continuous	Local	Fixed
Light Field	Continuous	None	Fixed
Movie Map	Discrete	None	Fixed
Panorama	Rotation	None	Fixed
Image	None	None	Fixed

- ## IBR: A brief history
- Texture maps, bump maps, environment maps [70s]
 - Poggio MIT 90s: Faces, image-based analysis/synthesis
 - Mid-Late 90s
 - Chen and Williams 93, View Interpolation [Images+depth]
 - Chen 95 Quicktime VR [Images from many viewpoints]
 - McMillan and Bishop 95 Plenoptic Modeling [Images w disparity]
 - Gortler et al, Levoy and Hanrahan 96 Light Fields [4D]
 - Shade et al. 98 Layered Depth Images [2.5D]
 - Debevec et al. 00 Reflectance Field [4D]
 - Inverse rendering (Marschner, Sato, Yu, Boivin,...)
 - Today: IBR hasn't replaced conventional rendering, but has brought sampled and data-driven representations to graphics

Game #1: increase the dimensionality

2D rgb	texture
2D rgbz	range image
2.5D rgb _{oz}	layered depth images
4D rgb	light field / Lumigraph
4D rgbz	array of range images
4.5D rgb _{oz}	layered light fields

© 1997 Marc Levoy

Game #2: replace the quantity represented

4D rgb	light field / Lumigraph
$\{u, v, s, t\}$	
5D rgb	plenoptic function
$\{x, y, z\} \times \{\theta, \phi\}$	
6D ρ	free-space BRDF field
$\{u, v, s, t\} \times \{\theta, \phi\}$	
7D ρ	BRDF volume
$\{x, y, z\} \times \{\theta_1, \phi_1, \theta_2, \phi_2\}$	

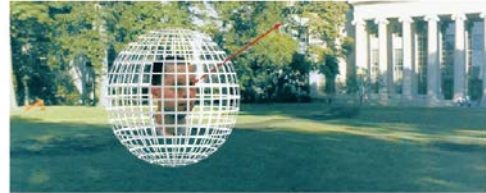
© 1997 Marc Levoy

Outline

- Overview of IBR
- Basic approaches
 - Image Warping
 - [2D + depth. Requires correspondence/disparity]
 - Light Fields [4D]
 - Survey of some early work



Images as a Collection of Rays



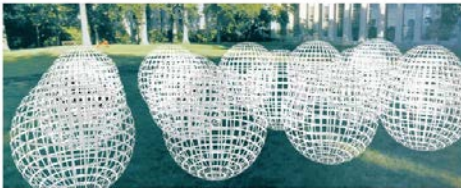
An image is a subset of the rays seen from a given point
- this "space" of rays occupies two dimensions

Warping slides courtesy Leonard McMillan, SIGGRAPH 99 course notes



The Plenoptic Function

- ✓ The set of rays seen from all points ...

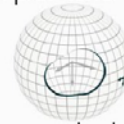


$$p = P(\theta, \phi, x, y, z, \lambda, t)$$



Image-based rendering is about

...reconstructing a plenoptic function from a set of samples taken from it.



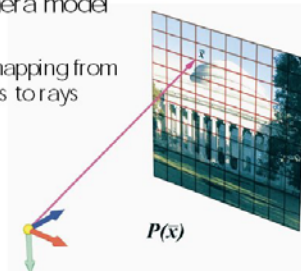
- ✓ Ignoring time, and selecting a discrete set of wavelengths gives a 5-D plenoptic function



Where to Begin?

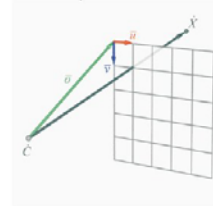
- ✓ Pinhole camera model

- Defines a mapping from image points to rays in space



Mapping from Rays to Points

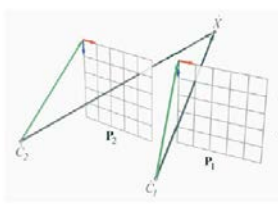
- ✓ Simple Derivation



$$P = \begin{bmatrix} u_x & v_x & o_x \\ u_y & v_y & o_y \\ u_z & v_z & o_z \end{bmatrix}$$

$$\vec{X} = \vec{C} + t P \vec{x}$$

Correspondence



$$\begin{aligned}\hat{C}_2 + t_2 P_2 \bar{x}_2 &= \hat{C}_1 + t_1 P_1 \bar{x}_1 \\ t_2 P_2 \bar{x}_2 &= \hat{C}_1 - \hat{C}_2 + t_1 P_1 \bar{x}_1 \\ t_2 \bar{x}_2 &= P_2^{-1}(\hat{C}_1 - \hat{C}_2) + t_1 P_2^{-1} P_1 \bar{x}_1 \\ \frac{t_2}{t_1} \bar{x}_2 &= \frac{1}{t_1} P_2^{-1}(\hat{C}_1 - \hat{C}_2) + P_2^{-1} P_1 \bar{x}_1 \\ \bar{x}_2 &= \underbrace{\frac{1}{t_1} P_2^{-1}(\hat{C}_1 - \hat{C}_2)}_{\hat{H}_{21}} + \underbrace{P_2^{-1} P_1}_{H_{21}} \bar{x}_1\end{aligned}$$

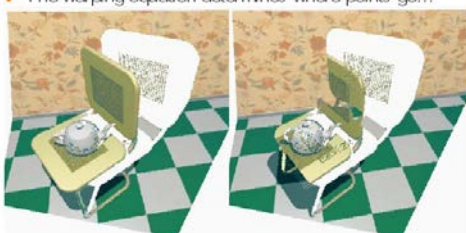
Warping in Action

✓ A 3D Warp



Visibility

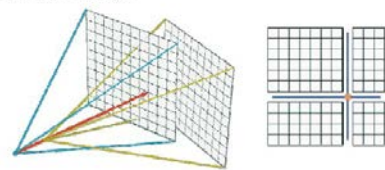
✓ The warping equation determines where points go...



... but that is not sufficient

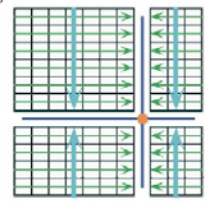
Partition Reference Image

✓ Project the desired center-of-projection onto the reference image



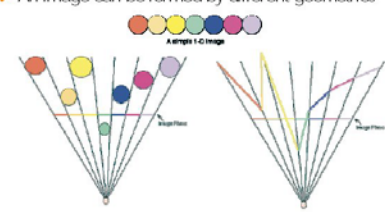
Enumeration

- ✓ Drawing toward the projected point guarantees an *occlusion compatible* ordering
- ✓ Ordering is consistent with a painter's algorithm
- ✓ Independent of the scene's contents
- ✓ Easily generalized to other viewing surfaces
- ✓ No auxiliary information required



Reconstruction

- ✓ Typical images are discrete, not continuous
- ✓ An image can be formed by different geometries



Outline

- Overview of IBR
- Basic approaches
 - Image Warping
 - [2D + depth. Requires correspondence/disparity]
 - *Light Fields [4D]*
 - Survey of some early work

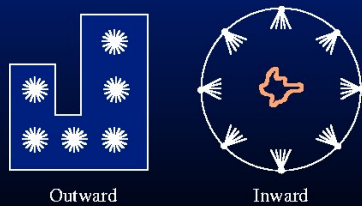
Light Field Rendering

Marc Levoy Pat Hanrahan



Computer Science Department
Stanford University

Apple's QuickTime VR



Generating New Views

Problem: fixed vantage point/center


One Solution: view interpolation

- Interpolating between range images (Chen and Williams, 1993)
- Correspondences and epipolar analysis (McMillan and Bishop, 1995)

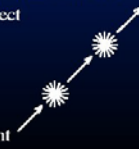
-> Requires depths or correspondences:

must be extracted from acquired imagery
relatively expensive and error-prone morph

Light Fields

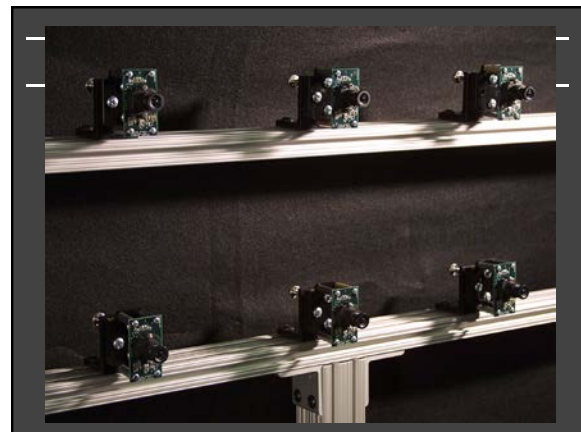
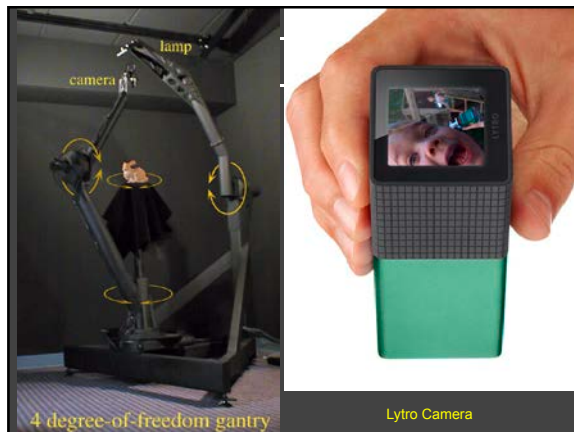
Gershun's and Moon's idea of a light field: 
Radiance as a function of a ray or line: $L(x, y, z, \theta, \phi)$

- In "free space" (no occluders) 5D reduces to 4D
 - Exterior of the convex hull of an object
 - Interior of an environment
- Images are 2D slices
 - Insert acquired imagery
 - Extract image from a given viewpoint



4D Light Field





Light Field as a 2D Array of Image

Camera Array

$L(r) = L(u, v, s, t)$

Dual Interpretation of Light Field

Plenoptic Light Field
Field radiance

UV Array of ST Images

Surface Light Field
Surface radiance

ST Array of UV Images

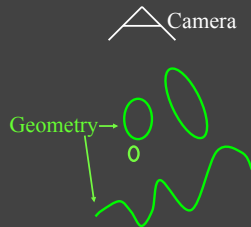
Compression Example

Original Compressed 120:1

Outline

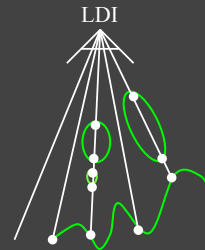
- Overview of IBR
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Layered Depth Images [Shade 98]

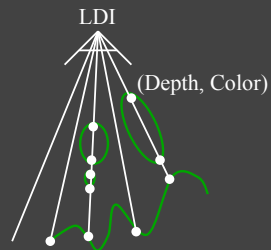


Slide from Agrawala, Ramamoorthi, Heinrich, Moll, SIGGRAPH 2000

Layered Depth Images [Shade 98]



Layered Depth Images [Shade 98]



Surface Light Fields

- Miller 98, Nishino 99, Wood 00
- Reflected light field (lumisphere) on surface
- Explicit geometry as against light fields. Easier compress

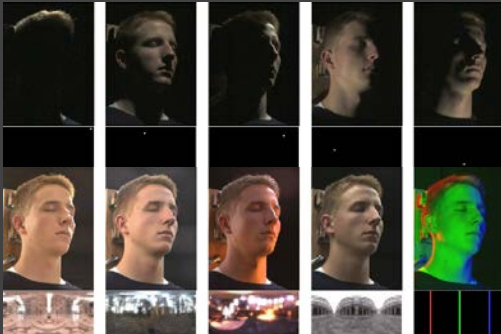


Acquiring Reflectance Field of Human Face [Debevec et al. SIGGRAPH 00]

Illuminate subject from many incident directions



Example Images



Outline

- Overview of IBR
- Basic approaches
 - Image Warping
 - [2D + depth. Requires correspondence/disparity]
 - Light Fields [4D]
 - *Survey of some recent work*
 - *Sampled data representations*

Conclusion (my views)

- IBR initially spurred great excitement: revolutionize pipeline
- But, IBR in pure form not really practical
 - WYSIAYG
 - Explosion as increase dimensions (8D transfer function)
 - Good compression, flexibility needs at least implicit geometry/BRDF
- Real future is sampled representations, data-driven method
 - Acquire (synthetic or real) data
 - Good representations for interpolation, fast rendering
 - Much of visual appearance, graphics moving in this direction
- Understand from Signal-Processing Viewpoint
 - Sampling rates, reconstruction filters
 - Factored representations, Fourier analysis
- Light Fields fundamental in many ways, including imaging